

**FINAL PROGRESS REPORT**

**METAL-MATRIX COMPOSITES AND POROUS MATERIALS:  
CONSTITUTIVE MODELS, MICROSTRUCTURE EVOLUTION AND  
APPLICATIONS**

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14. ABSTRACT Constitutive models were developed and implemented numerically to account for the evolution of microstructure and anisotropy in finite-deformation processes involving porous and composite materials. Use was made of rigorous homogenization procedures developed by the PI under an earlier grant (AFOSR 89-0288). The constitutive models developed took a standard internal-variable form depending on suitably derived internal variables (serving to characterize the current state of the microstructure) and differential evolution laws for these variables. The main findings of the work are: (a) the evolution of the microstructure affects quite significantly the macroscopic response of porous materials; (b) there is synergistic coupling between the various microstructural variables, in particular, between the porosity and anisotropy; (c) qualitative agreement has been found with available experimental results, particularly for the non-uniform evolution of porosity and anisotropy in forming processes. The particular case of porous metals was considered in detail and the newly developed constitutive models were implemented in a general-purpose, finite-strain finite element program. Several problems in the area of metal forming were then analyzed, and implications for the onset of shear instabilities was explored.				
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## **1. Grant Number**

AFOSR F49620-97-1-0212

## **2. Objectives**

The objective of this work is to develop constitutive models that are capable of accounting for the evolution of microstructure in finite-deformation processes of heterogeneous materials. The models to be developed, through rigorous homogenization procedures for random microstructures, will take the form of standard homogenized constitutive models, which will depend explicitly on appropriate internal variables (serving to characterize the current state of the microstructure), and will be supplemented by differential evolution laws for these internal variables. The particular case of a porous metal will be considered in some detail and the newly developed constitutive models will be implemented in a general-purpose, finite-strain finite element program. Several problems in the areas of metal forming will then be analyzed, and implications for the onset of shear instabilities will be explored. Finally, comparisons with experimental results and further refinements of the models will be carried out, for porous aluminum and aluminum-matrix composites.

## **3. Status of effort**

This project has been completed as of 12/31/99.

## **3. Accomplishments**

The developed constitutive models are the first of their type to be able to account for deformation-induced anisotropy in porous materials and particle-reinforced composites. The main findings of the work are: (a) the evolution of the microstructure affects quite significantly the macroscopic response of porous materials; (b) there significant coupling between the various microstructural variables, in particular, between the porosity and anisotropy; (c) qualitative agreement has been found with available experimental results, particularly for the evolution of porosity and anisotropy in forming processes. A constitutive subroutine (UMAT) for the model has been successfully implemented in ABAQUS and tested for several different types of forming processes, including plane-strain and axisymmetric extrusion and tapered-disk compaction. In the context of future work, we will explore further the implications of microstructure evolution on the overall stability of deformation processes and consider applications to problems where microstructure evolution is significant, including ductile fracture, high-strain rate (explosive loading) applications and impact loading.

## **5. Personnel**

The PI was supported for one month/year of summer salary for his efforts on this project. In addition, one former graduate student, M. Kailasam, now employed by HKS (the makers of ABAQUS), assisted with the computations on his free time. In addition, Professor Nick Aravas, now at the University of Thessaly (Greece) collaborated with us on the numerical implementation of the constitutive model and in the writing of the papers.

## **6. Publications**

### Sponsored by AFOSR

M. Kailasam, N. Aravas and P. Ponte Castañeda. "Constitutive models for porous materials with developing anisotropy and application to deformation processing." *Computational Mechanics* (1999): to appear.

N. Aravas, M. Kailasam and P. Ponte Castañeda. "Constitutive Models for Porous Media with Microstructure Evolution: Computational Issues." *Proceedings of the 3rd National Congress on Computational Mechanics*, Volos (Greece), pp. 65-72, 1999.

P. Ponte Castañeda and J. R. Willis. "Variational second-order estimates for nonlinear composites." *Proceedings of the Royal Society of London A* **455**(1999): 1799-1812.

M. Kailasam and P. Ponte Castañeda. "A general constitutive theory for linear and nonlinear particulate media with evolving microstructure." *Journal of the Mechanics and Physics of Solids* **46** (1998): 427-465.

M. Nebozhyn and P. Ponte Castañeda. "Exact second-order estimates of the self-consistent type for nonlinear composite materials." *Mechanics of Materials* **28** (1998): 9-22.

### Related work sponsored by other agencies.

M. Nebozhyn, P. Gilormini and P. Ponte Castañeda. "Variational self-consistent estimates for cubic viscoplastic polycrystals: The effects of grain anisotropy and shape." *Journal of the Mechanics and Physics of Solids* (2000): submitted for publication.

M. Nebozhyn, P. Gilormini and P. Ponte Castañeda. "Variational self-consistent estimates for viscoplastic polycrystals with highly anisotropic grains." *Comptes Rendus de l'Académie des Sciences, Paris, Série IIb* (2000): communicated.

P. Ponte Castañeda and E. Tiberio. "A second-order homogenization procedure in finite elasticity and applications to black-filled elastomers." *Journal of the Mechanics and Physics of Solids* (2000): in press.

M. Nebozhyn and P. Ponte Castañeda. "The second-order procedure: Exact versus approximate results for isotropic, two-phase composites." *Journal of the Mechanics and Physics of Solids* **47** (1999): 2171-2185..

P. Ponte Castañeda and E. Tiberio. "Homogenization estimates for hyperelastic composites and applications to particle-reinforced rubbers." *Comptes Rendus de l'Académie des Sciences, Paris, Série IIb* **327** (1999): 1297-1304.

K. Bose, P. A. Mataga and P. Ponte Castañeda. "Stable crack growth along a brittle/ductile interface. interface - II. Small scale yielding solutions and interfacial toughness predictions." *International Journal of Solids and Structures* **36** (1998): 1-34.

M. Bornert and P. Ponte Castañeda. "Second-order estimates of the self-consistent type for viscoplastic polycrystals." *Proceedings of the Royal Society of London A* **454** (1998): 3035-3045

P. Ponte Castañeda and P. Suquet. "Nonlinear composites." *Advances in Applied Mechanics* **34** (1998): 171-302.

P. Ponte Castañeda. "Three-point bounds and other estimates for strongly nonlinear composites." *Physical Review B* **57** (1998): 12077-12083.

M. Nebozhyn and P. Ponte Castañeda. "Second-order estimates for the effective behavior of nonlinear porous materials." In *Transformation Problems in Composite and Active Materials (IUTAM Symposium)*, edited by Y. Bahei-El-Din and G. J. Dvorak, 73-88. New York: Kluwer, 1998.

M. Nebozhyn and P. Ponte Castañeda. "Variational estimates of the self-consistent type for creep of polycrystalline materials." In *Micro- and Macrostructural Aspects of Thermoplasticity (IUTAM Symposium)*, edited by O. T. Bruhns and E. Stein, 207-215. New York: Kluwer, 1998.

P. Ponte Castañeda. "Nonlinear polycrystals with crystallographic and morphological texture evolution." In *Continuum Models and Discrete Systems (CMDS 9)*, edited by E. Inan and K. Z. Markov, 228-235. Singapore: World Scientific, 1998.

#### Ph.D. Thesis

M. Kailasam (1999) A general constitutive theory for particulate composites and porous materials with microstructure evolution. University of Pennsylvania.

### Books Edited

P. Ponte Castañeda and P. Suquet (Guest Eds.), The John R. Willis 60<sup>th</sup> Anniversary Issue, *Journal of the Mechanics and Physics of Solids* **48** (2000): 400 pages.

### **7. Interactions**

#### Technical Committees

ASME Technical Committee on Instability in Solids and Structures, Member.

#### Seminars

"Microstructure evolution in porous and particle-reinforced composites." Laboratoire de Mécanique des Solides, *Ecole Polytechnique* (France), June 22, 1998.

"Nonlinear homogenization and applications." Department of Materials Science, *Universidad Politecnica de Madrid*, June 28, 1999.

"Homogenization estimates in finite elasticity and applications to particle-reinforced elastomers." *Isaac Newton Institute for Mathematical Sciences*, Cambridge University, September 12, 1999.

"Microstructure evolution in porous and composite materials: Implications for shear localization." *Isaac Newton Institute for Mathematical Sciences*, Cambridge University, October, 1999.

#### Invited Conference Presentations

"Micromechanics of Nonlinear Composites." *9th International Symposium on Continuum Models and Discrete Systems*, Istanbul (Turkey), June 29-July 3, 1998.

"Microstructure evolution in particle-reinforced systems." *7th International Symposium on Plasticity and its Current Applications*, Cancun (Mexico), January 5-13, 1999.

"Nonlinear Homogenization and Applications." *7th International Symposium on Plasticity*, Cancun (Mexico), January 5-13, 1999.

"Constitutive Models for Porous Media with Microstructure Evolution and Application to Forming." *3rd National Congress on Computational Mechanics*, Volos (Greece), June 24-26, 1999.

### Transitions

Re-initiated contact with Dr. Richard Becker, formerly at ALCOA, and now at Lawrence Livermore. Dr. Becker has proposed the implementation of our anisotropic constitutive model for porous metals into the computer programs at LLNL, as part of the ASCI initiative. If the project is approved, the constitutive model will be extended for the materials of interest at LLNL and implemented numerically.

### **8. Honors and Awards**

Associate Editor, 1999-.

*Comptes Rendus de l'Académie des Sciences de Paris, Série IIb, Mécanique.*

Two lectures at the Isaac Newton Institute Program on Mathematical Developments in Solid Mechanics and Materials Science, University of Cambridge, September-December 1999.

Invited to participate and lecture in the Workshop on "Homogenization and Effective Media Theories." *Mathematical Sciences Research Institute, Berkeley, March 6-17, 2000.*

Invited to give a "Sectional Lecture" on "Nonlinear Composites" at the upcoming 20<sup>th</sup> International Congress of Theoretical and Applied Mechanics, August 2000.

## **9. Appendix: The finite element program**

N.f

```
c
C----- UMAT routine
      subroutine umat(stress,statev,ddsdde,sse,spd,scd,
     &           rpl,ddsdde,drplde,drpldt,
     & stran,dstran,time,dtime,temp,dtemp,predef,dpred,cname,
     & ndi,nshr,ntens,nstatv,props,nprops,coords,drot,pnewdt,
     & celent, dfgrd0,dfgrd1,noel,npt,layer,kspt,kstep,kinc)

c      include 'ABA_PARAM.INC'
      character*8 cname
      real*8 stress(ntens),statev(nstatv),ddsdde(ntens,ntens)
      real*8 ddsddt(ntens),drplde(ntens),stran(ntens),dstran(ntens)
      real*8 time(2),predef(1),dpred(1),props(nprops),coords(3)
      real*8 drot(3,3),dfgrd0(3,3),dfgrd1(3,3)
      real*8 sse,spd,scd,rpl,drpldt,dtime,temp,dtemp
      real*8 pnewdt,celent,ct,st,sp,cs,ss
      integer ntens,ndi,nshr,nstatv,nprops,noel,npt,layer
      integer kspt,kstep,kinc,i,j,inpt

c      real*8 mule,kle,mu2e,ek2e
      real*8 s(3,3),strain(3,3),ddsdde_mine(6,6)
      real*8 f,wil,wi2,diam,atheta,aphi,apsi
      real*8 sc(6),strainc(6),dummy3(3,3)
      real*8 dummy1(3,3),R(3,3),RT(3,3),dummy2(3,3)
      real*8 mul,k1,mu2,k2,sigy1,x2,xacc,sigy0,x1,hrd
      real*8 eps_plastic,k11,rtsafe,rot(3,3),rott(3,3)
      real*8 rtnewt,eigen(3,3),ei2(3),ei3(3),ei1(3)
      real*8 a,b,c,xb1,xb2
      real*8 func
      real*8 eigval(3)
      real*8 rota(3,3),rotj(3,3)
      real*8 tottheta,totphi,totpsi
      integer nb,num,n,np,nrot
      logical path,yield,check,neg,debug
      logical evolf,evolwi,evolti
      logical zb,cal
      common /controls/evolf,evolwi,evolti
      common /mkmodulus/mul,k1,mu2,k2,sigy0,k11
      common /mkelas/mule,kle,mu2e,ek2e
      common /mkdata1/f,wil,wi2,sc,strainc,eps_plastic,sigy1,hrd
      common /mkorient/cp,sp,ct,st,cs,ss,rot,rott,atheta,aphi,apsi
      common /mkdata2/yield,check,neg
      common /mkrot/R,RT,rotj
      common /mdebug/debug
      common /cal1/cal
      common /zbl/zb
      external func,rtsafe,funcd,rtnewt,zbrak
      path=.true.
      open(unit=15,file='/scratch/mahesh/data',
&status='unknown')
      open(unit=16,file='/scratch/mahesh/data1',
&status='unknown')

c
c----- Various parameters, like those used to turn the evolution of
c some of the micro. variables on/off etc. are entered below.
c      if ((noel.eq.150).or. (noel.eq.600)).and.(npt.eq.1) then
        write(15,*)'kinc',kinc,'npt',npt,'ntens',ntens
        write(15,*)'stress'
        write(15,*)stress
c      cal=.true.
c      call flush(15)
c      else
c        cal=.false.
c      endif
        evolf=.true.
        evolwi=.true.
        evolti=.true.
        debug=.false.
        if(debug.eq..true.) then
          write(15,*)'entry'
          call flush(15)
        endif
        inpt=npt
        yield=.false.
        neg=.false.
        mul=props(1)
        k1=props(2)
        mu2=props(3)
        k2=props(4)
        sigy0=props(5)
        mule=props(6)
        kle=props(7)
        mu2e=props(8)
        ek2e=props(9)
```

```

k11=k1*1.0
if(debug.eq..true.) then
write(15,*)'elas',mule,kle,mu2e,ek2e
call flush(15)
endif
do 1 i=1,3
  do 2 j=1,3
    if (dabs(dfgrd0(i,j)).lt.1.0d-14) then
      dfgrd0(i,j)=0.0
    endif
    if (dabs(dfgrd1(i,j)).lt.1.0d-14) then
      dfgrd1(i,j)=0.0
  endif
2  continue
1  continue
  do 3 i=1,6
    if (dabs(stress(i)).lt.1.0d-08) then
      stress(i)=0.0
    endif
 3  continue
c
c----- Convert stress to column form in MY notation
c----- The input comes in the form: {s11,s22,s33,s12,s13,s23}
c----- while I have always used
c       {s11,s22,s33,sqrt(2.0)*s12,sqrt(2.0)*s23,sqrt(2.0)*s31}.
c----- Below I convert the incoming stresses to MY notation
c----- Also note that in the case of use with plane-strain elements
c       only 4 components of the stress are provided by ABAQUS and these
c       are the 11,22,33 and 12 components. In my notation, plane calculations
c       are performed in the 2-3 plane. So care has to be taken
c       in converting to my notation.
if (ntens.eq.4) then
  sc(1)=stress(3)
  sc(2)=stress(1)
  sc(3)=stress(2)
  sc(4)=0.0
  sc(5)=dsqrt(2.D0)*stress(4)
  sc(6)=0.0
else
  sc(1)=stress(1)
  sc(2)=stress(2)
  sc(3)=stress(3)
  sc(4)=dsqrt(2.D0)*stress(4)
  sc(5)=dsqrt(2.D0)*stress(6)
  sc(6)=dsqrt(2.D0)*stress(5)
endif
s(1,1)=sc(1)
s(2,2)=sc(2)
s(3,3)=sc(3)
s(1,2)=sc(4)/dsqrt(2.D0)
s(2,3)=sc(5)/dsqrt(2.D0)
s(3,1)=sc(6)/dsqrt(2.D0)
s(2,1)=s(1,2)
s(3,2)=s(2,3)
s(1,3)=s(3,1)
c----- Decompose deltaF to get R and U
c----- Again, we must convert dfgrd0 to my notation:
if (ntens.eq.4) then
  dummy1(1,1)=dfgrd0(3,3)
  dummy1(2,2)=dfgrd0(1,1)
  dummy1(3,3)=dfgrd0(2,2)
  dummy1(1,2)=dfgrd0(3,1)
  dummy1(2,1)=dfgrd0(1,3)
  dummy1(2,3)=dfgrd0(1,2)
  dummy1(3,2)=dfgrd0(2,1)
  dummy1(1,3)=dfgrd0(3,2)
  dummy1(3,1)=dfgrd0(2,3)
else
  do 10 i=1,3
    do 20 j=1,3
      dummy1(i,j)=dfgrd0(i,j)
    continue
 10  continue
  endif
  call inverse3x3(dummy1,dummy2)
  if (ntens.eq.4) then
    dummy1(1,1)=dfgrd1(3,3)
    dummy1(2,2)=dfgrd1(1,1)
    dummy1(3,3)=dfgrd1(2,2)
    dummy1(1,2)=dfgrd1(3,1)
    dummy1(2,1)=dfgrd1(1,3)
    dummy1(2,3)=dfgrd1(1,2)
    dummy1(3,2)=dfgrd1(2,1)
    dummy1(1,3)=dfgrd1(3,2)

```

```

dummy1(3,1)=dfgrd1(2,3)
else
  do 11 i=1,3
    do 21 j=1,3
      dummy1(i,j)=dfgrd1(i,j)
    continue
  continue
endif
call matprod(dummy1,dummy2,dummy3)
call decompose(dummy3,R,strain,eigen,eigval)
c   write(16,*)'dfgrd11',dfgrd1(1,1),dfgrd1(1,2),dfgrd1(1,3)
c   write(16,*)'dfgrd12',dfgrd1(2,1),dfgrd1(2,2),dfgrd1(2,3)
c   write(16,*)'dfgrd13',dfgrd1(3,1),dfgrd1(3,2),dfgrd1(3,3)
c   write(16,*)'strain1',strain(1,1),strain(1,2),strain(1,3)
c   write(16,*)'strain2',strain(2,1),strain(2,2),strain(2,3)
c   write(16,*)'strain3',strain(3,1),strain(3,2),strain(3,3)
c----- Here we have obtained ln(delta_U) and R, the components of which are
c relative to the fixed Lab coords.
c   write(15,*)'eigen',eigen
c   call flush(15)
ei1(1)=eigen(1,1)
ei1(2)=eigen(1,2)
ei1(3)=eigen(1,3)
ei2(1)=eigen(1,2)
ei2(2)=eigen(2,2)
ei2(3)=eigen(3,2)
ei3(1)=eigen(1,3)
ei3(2)=eigen(2,3)
ei3(3)=eigen(3,3)
cwrite(15,*)'test1=',ei1(1)*ei2(1)+ei1(2)*ei2(2)+ei1(3)*ei2(3)
cwrite(15,*)'test2=',ei1(1)*ei3(1)+ei1(2)*ei3(2)+ei1(3)*ei3(3)
cwrite(15,*)'test3=',ei2(1)*ei3(1)+ei2(2)*ei3(2)+ei2(3)*ei3(3)
cwrite(15,*)'test4=',ei1(1)*ei1(1)+ei1(2)*ei1(2)+ei1(3)*ei1(3)
cwrite(15,*)'test5=',ei2(1)*ei2(1)+ei2(2)*ei2(2)+ei2(3)*ei2(3)
cwrite(15,*)'test6=',ei3(1)*ei3(1)+ei3(2)*ei3(2)+ei3(3)*ei3(3)
c   write(15,*)'t7',eigval(1),' ',ei1(1),ei1(2),ei1(3)
c   write(15,*)'t8',eigval(2),' ',ei2(1),ei2(2),ei2(3)
c   write(15,*)'t9',eigval(3),' ',ei3(1),ei3(2),ei3(3)
if ((kinc.eq.1).and.(kstep.eq.1)) then
  f=0.15
  wi1=1.0001
  wi2=1.0001
atheta=0.0
aphi=0.0
apsi=0.0
tottheta=0.0
totphi=0.0
totpsi=0.0
do 777 i=1,3
  do 778 j=1,3
    if (i.ne.j) then
      rotj(i,j)=0.0
    else
      rotj(i,j)=1.0
    endif
    continue
  continue
778
777
statev(1)=f
sigy1=props(5)
statev(2)=wi1
statev(3)=wi2
statev(4)=atheta
statev(5)=aphi
statev(6)=apsi
statev(7)=0.0
statev(8)=props(5)
statev(9)=0.0
statev(10)=hrd
statev(11)=wi1/wi2
statev(12)=rotj(1,1)
statev(13)=rotj(1,2)
statev(14)=rotj(1,3)
statev(15)=rotj(2,1)
statev(16)=rotj(2,2)
statev(17)=rotj(2,3)
statev(18)=rotj(3,1)
statev(19)=rotj(3,2)
statev(20)=rotj(3,3)
statev(21)=tottheta
statev(22)=totphi
statev(23)=totpsi
statev(24)=1.0/wi2
statev(25)=(1.0/wi2)*wi1
endif

```

```

do 5 i=1,3
do 6 j=1,3
  if (dabs(R(i,j)).lt.1.0d-14) then
    R(i,j)=0.0
  endif
6      continue
5      continue
do 100 i=1,3
  do 110 j=i,3
    RT(i,j)=R(j,i)
110    continue
100   continue
c----- BEGIN TEST1
c----- This is a test to see if the components of [drot][s]_t[drot_transpose]
c      that ABAQUS gives me are with respect to the fixed frame. So, what I
c      do below is assume that this is true (they are with respect to the
c      GLOBAL axes) and then use transformation laws to obtain the components
c      w.r.t to a frame which is obtained from the GLOBAL frame by a rotation
c      of drot. These components are the same as the components of [s]_t w.r.t
c      the GLOBAL frame. I then check if these values agree with the stress
c      of the previous increment: this is output in the .dat file and since
c      all tensors are stored w.r.t the GLOBAL axes, the stress output should
c      agree with 'dummy2' below and they do!
c      write(15,*)'stress_1'
c      dummy2(1,1)=stress(1)
c      dummy2(2,2)=stress(2)
c      dummy2(3,3)=stress(3)
c      dummy2(1,2)=stress(4)
c      dummy2(2,1)=stress(4)
c      dummy2(2,3)=stress(6)
c      dummy2(3,2)=stress(6)
c      dummy2(3,1)=stress(5)
c      dummy2(1,3)=stress(5)
c      call matprod(RT,dummy2,dummy1)
c      call matprod(dummy1,R,dummy2)
c      write(15,*)dummy2
c----- END TEST1
c----- BEGIN TEST2
c----- From dfgrd0 and dfgrd1, I have obtained ln(delta_U) and R. R is exactly
c      the same as drot. The dstran that ABAQUS provides me is ln(delta_V) and
c      its components are w.r.t the GLOBAL axes. I have the components of
c      ln(delta_U) also w.r.t the GLOBAL axes. It can be easily checked to
c      see that they have the same eigen values. Also [R][ln(delta_U)][RT]
c      must give us dstran.
c      write(15,*)'R'
c      write(15,*)R
c      write(15,*)'drot'
c      write(15,*)drot
c      do 31 i=1,3
c        do 32 j=1,3
c          dummy1(i,j)=strain(i,j)
c32      continue
c31      continue
c      n=3
c      np=3
c      call jacobi(dummy1,n,np,eigval,dummy2,nrot)
c      write(15,*)'Eigen values of ln(delta_U)'
c      write(15,*)eigval
c      do 33 i=1,3
c        do 34 j=1,3
c          dummy1(i,j)=strain(i,j)
c34      continue
c33      continue
c      write(15,*)'ln(delta_U)'
c      write(15,*)dummy1(1,1),dummy1(2,2),dummy1(3,3),dummy1(1,2)*2.0,
c      &dummy1(3,1)*2.0,dummy1(2,3)*2.0
c      call matprod(RT,dummy1,dummy2)
c      call matprod(dummy2,R,dummy1)
c      write(15,*)'ln(delta_V) from ln(delta_U)'
c      write(15,*)dummy1(1,1),dummy1(2,2),dummy1(3,3),dummy1(1,2)*2.0,
c      &dummy1(3,1)*2.0,dummy1(2,3)*2.0
c      write(15,*)'ln(delta_V)'
c      write(15,*)dstran
c----- END TEST2
c----- Stress components that abaqus provides me are w.r.t GLOBAL
c      co-ordinate frame. Since this is a finite-deformation problem,
c      the stress that I have here is one that has been rotated by 'drot',
c      i.e, it is [drot] [stress]_t [drot_transpose], but the components
c      are w.r.t the fixed GLOBAL frame. The integration algorithm that
c      I use requires that I used [stress]_t and NOT the above quantity.
c      This is done below:
c
c      call matprod(RT,s,dummy1)
c      call matprod(dummy1,R,s)

```

```

c
c-----Note that R and drot are exactly the same. The components of s are
c still relative to the global frame.
c
c An important interpretation of why we use the stress in the GLOBAL
c coordinate frame is that when we add to this the change in stress
c we get the new stress components relative to a coordinate frame
c which is obtained from the global frame by a rotation of drot. This
c stress is called sig_hat_n+1 in Dr. Aravas's notes. We see that to
c recover stress_n+1, we must pre and post multiply by R and RT,
c respectively. This is nothing but expressing the new stress components
c relative the GLOBAL frame.
c
c Note that we need not use the GLOBAL frame as one where all components
c are stored. In fact, we find it convenient to perform our integration
c relative to a coordinate frame which coincides with the orientation
c of the particles. What this implies is that, we transform the stress
c we have obtained above to this (particle orientation frame) coordinate
c frame and perform our integration there. The stress components that we
c then obtain are then w.r.t a coordinate frame which has is obtained
c from the particle orientation frame by a rotation of drot. We then
c again transform the stress (and other variables) to be expressed
c relative to the GLOBAL frame.
c
sc(1)=s(1,1)
sc(2)=s(2,2)
sc(3)=s(3,3)
sc(4)=dsqrt(2.D0)*s(1,2)
sc(5)=dsqrt(2.D0)*s(2,3)
sc(6)=dsqrt(2.D0)*s(3,1)
if ((kinc.gt.1).or.(kstep.gt.1)) then
  f=statev(1)
  wi1=statev(2)
  wi2=statev(3)
c=1.000
a=c/wi1
b=c/wi2
  atheta=statev(4)
  aphi=statev(5)
  apsi=statev(6)
  eps_plastic=statev(7)
  sigyl=statev(8)
rotj(1,1)=statev(12)
rotj(1,2)=statev(13)
rotj(1,3)=statev(14)
rotj(2,1)=statev(15)
rotj(2,2)=statev(16)
rotj(2,3)=statev(17)
rotj(3,1)=statev(18)
rotj(3,2)=statev(19)
rotj(3,3)=statev(20)
tottheta=statev(21)*3.14159/180.0
totphi=statev(22)*3.14159/180.0
totpsi=statev(23)*3.14159/180.0
if (f.lt.0.001) then
  evolf=.false.
  evolwi=.false.
  endif
if (wi2.lt.0.02) then
  evolwi=.false.
  endif
  endif
c----- The increment of strain below (corresponds to ln(delta_U)) is w.r.t
c GLOBAL coordinate frame.
strainc(1)=strain(1,1)
strainc(2)=strain(2,2)
strainc(3)=strain(3,3)
strainc(4)=strain(1,2)*dsqrt(2.D0)
strainc(5)=strain(2,3)*dsqrt(2.D0)
strainc(6)=strain(3,1)*dsqrt(2.D0)
c
c----- Expressing stress and strain in local coordinates:
c The integration problem is carried out in a co-ordinate frame
c which coincides with the orientation of the particles. This is
c done because it is more economical to rotate the stress and the
c strain once rather than having to rotate 4th order tensors like
c Amat, Bmat, MHS etc. whose components are readily obtained w.r.t
c the co-ordinate frame which coincides with the particle orientation.
c
99  ct=dcos(atheta)
    st=dsin(atheta)
    cp=dcos(aphi)
    cs=dcos(apsi)
    sp=dsin(aphi)

```

```

ss=dsin(apsi)
rota(1,1)=cs*cp-ss*ct*sp
rota(1,2)=-cs*sp-ss*ct*cp
rota(1,3)=ss*st
rota(2,1)=ss*cp+cs*ct*sp
rota(2,2)=-ss*sp+cs*ct*cp
rota(2,3)=-cs*st
rota(3,1)=st*sp
rota(3,2)=st*cp
rota(3,3)=ct
call matprod(rota,rotj,rot)
do 7 i=1,3
  do 8 j=1,3
    rott(i,j)=rot(j,i)
  continue
8
7
c----- Below the components of the stress are expressed w.r.t. the
c a coordinate system which instantaneously coincides with the
c orientation of the particles.
  call matprod(rott,s,dummy1)
  call matprod(dummy1,rot,s)
  sc(1)=s(1,1)
  sc(2)=s(2,2)
  sc(3)=s(3,3)
  sc(4)=dsqrt(2.D0)*s(1,2)
  sc(5)=dsqrt(2.D0)*s(2,3)
  sc(6)=dsqrt(2.D0)*s(3,1)
c----- Rotating below to express strain w.r.t the orientation of particles.
  call matprod(rott,strain,dummy1)
  call matprod(dummy1,rot,strain)
  strainc(1)=strain(1,1)
  strainc(2)=strain(2,2)
  strainc(3)=strain(3,3)
  strainc(4)=strain(1,2)*dsqrt(2.D0)
  strainc(5)=strain(2,3)*dsqrt(2.D0)
  strainc(6)=strain(3,1)*dsqrt(2.D0)
c----- Integrating to obtain the stress and the new state variables.
  xacc=1.0d-9
  if ((strainc(1).eq.0.0).and.(strainc(2).eq.0.0)
  & .and.(strainc(3).eq.0.0).and.(strainc(4).eq.0.0)
  & .and.(strainc(5).eq.0.0).and.(strainc(6).eq.0.0)) then
    dlam=0.0
    go to 4
  endif
  call guessmaker(x2)
  if (yield.eq..false.) then
    dlam=0.0
    go to 4
  endif
  if (neg.eq..true.) then
    pnewdt=0.75
    write(15,*)"This should never happen!"
    call flush(15)
    return
  endif
  if (x2.lt.0.0) then
    write(15,*)"Guessmaker screwed up",x2
    call flush(15)
  endif
c----- Trying to bracket a solution for delta_lambda
  x2=0.02
  x1=1.0d-10
  num=20
  nb=1
  call zbrak(func,x1,x2,num,xb1,xb2,nb)
  if (neg.eq..true.) then
    pnewdt=0.75
  return
  endif
  if (nb.eq.0) then
    write(15,*)"bracketing problem: Level 1"
    call flush(15)
    x1=1.0d-10
    num=50
    nb=1
    call zbrak(func,x1,x2,num,xb1,xb2,nb)
    if (neg.eq..true.) then
      pnewdt=0.75
      return
    endif
  endif
  if (nb.eq.0) then
    write(15,*)"bracketing problem: Level 2"
    call flush(15)
  endif

```

```

zb=.true.
  x1=1.0d-10
  num=200
  nb=1
  call zbrak(func,x1,x2,num,xb1,xb2,nb)
  if (neg.eq..true.) then
    pnewdt=0.75
    return
  endif
  endif
  if (nb.eq.0) then
    write(15,*)"bracketing problem: Level critical"
  call flush(15)
  x1=1.0d-10
  num=500
  nb=1
  call zbrak(func,x1,x2,num,xb1,xb2,nb)
  if (neg.eq..true.) then
    pnewdt=0.75
    return
  endif
  endif
  endif
zb=.false.
  if (nb.eq.0) then
    pnewdt=0.75
    write(15,*)"Bracketing Failure"
  call flush(15)
  return
  endif
c----- Using a combined secant/bisection procedure to find the solution for
c      delta_lambda.
c
c      dlam=rtsafe(funcd,xb1,xb2,xacc)
c      write(15,*)"dlam",dlam,'kinc',kinc
c      if (neg.eq..true.) then
c        pnewdt=0.75
c        write(15,*)"returned after unsuccessful rtsafe",kinc,noel,npt
c      call flush(15)
c      return
c      endif
c----- Initializing theta: The voids start evolving at an orientation given
c      by the eigen values of the right-stretch tensor. The orientation of the
c      voids makes sense only when the voids are not spherical anymore. This
c      means that the following steps are carried out only when the material
c      has started deforming plastically.
c      if (evolti.eq..true.) then
c        if (statev(9).eq.0.0) then
c          write(15,*)"ei2",ei2
c          write(15,*)"ei3",ei3
c        cwrite(15,*)"thetaj",dacos(rotj(3,3))
c        call flush(15)
c        if (dabs(ei2(3)).gt.1.0d-10) then
c          if (eigval(3).gt.eigval(2)) then
c            if ((ei2(3).lt.0.0).and.(ei2(2).gt.0.0)) then
c              atheta=-dacos(ei2(2))
c              write(15,*)"theta_initializing_a",noel,npt
c            else if ((ei2(3).gt.0.0).and.(ei2(2).gt.0.0)) then
c              atheta=dacos(ei2(2))
c              write(15,*)"theta_initializing_b",noel,npt
c            else if ((ei2(3).gt.0.0).and.(ei2(2).lt.0.0)) then
c              write(15,*)"theta_initializing:warning1"
c              atheta=dacos(ei2(2))
c            else if ((ei2(3).lt.0.0).and.(ei2(2).lt.0.0)) then
c              atheta=-dacos(ei2(2))
c              write(15,*)"theta_initializing:warning2"
c            else
c              atheta=0.0
c            endif
c            else if (eigval(3).lt.eigval(2)) then
c              if ((ei2(3).lt.0.0).and.(ei2(2).gt.0.0)) then
c                atheta=(3.14159/2.0)-dacos(ei2(2))
c                write(15,*)"theta_initializing_c",noel,npt
c              else if ((ei2(3).gt.0.0).and.(ei2(2).gt.0.0)) then
c                atheta=-((3.14159/2.0)-dacos(ei2(2)))
c                write(15,*)"theta_initializing_d",noel,npt
c              else if ((ei2(3).gt.0.0).and.(ei2(2).lt.0.0)) then
c                write(15,*)"theta_initializing:warning3"
c                atheta=-dacos(ei2(2))
c              else if ((ei2(3).lt.0.0).and.(ei2(2).lt.0.0)) then
c                atheta=dacos(ei2(2))
c                write(15,*)"theta_initializing:warning4"
c              else
c                atheta=0.0
c              endif

```

```

    else
      write(15,'voids are spherical:problems'
      endif
      atheta=0.0
      statev(9)=statev(9)+1.0
      write(15,'sending back'
      call flush(15)
      go to 99
    else
      atheta=0.0
      statev(9)=statev(9)+1.0
    endif
  endif
c----- Using the solution for 'dlam' (delta_lambda) to update all variables:
4  call update(dlam,ddsdde_mine)
  if ((f.lt.0.0).or.(wi1.lt.0.0).or.(wi2.lt.0.0)) then
    pnewdt=0.75
    write(15,'This should never happen: problem should have been
& taken care of before updating',dlam,f,wi1,wi2
    call flush(15)
    return
  endif
c----- stress and ddsdde are relative to the GLOBAL axes.
  s(1,1)=sc(1)
  s(2,2)=sc(2)
  s(3,3)=sc(3)
  s(1,2)=sc(4)/dsqrt(2.D0)
  s(2,3)=sc(5)/dsqrt(2.D0)
  s(3,1)=sc(6)/dsqrt(2.D0)
  s(2,1)=s(1,2)
  s(3,2)=s(2,3)
  s(1,3)=s(3,1)
  sc(1)=s(1,1)
  sc(2)=s(2,2)
  sc(3)=s(3,3)
  sc(4)=s(1,2)*dsqrt(2.D0)
  sc(5)=s(2,3)*dsqrt(2.D0)
  sc(6)=s(3,1)*dsqrt(2.D0)
  if (intens.eq.4) then
    stress(1)=sc(2)
    stress(2)=sc(3)
    stress(3)=sc(1)
    stress(4)=sc(5)/dsqrt(2.D0)
  else
    stress(1)=sc(1)
    stress(2)=sc(2)
    stress(3)=sc(3)
    stress(4)=sc(4)/dsqrt(2.D0)
    stress(5)=sc(6)/dsqrt(2.D0)
    stress(6)=sc(5)/dsqrt(2.D0)
  endif
  statev(1)=f
  if ((statev(3).gt.1.0).and.(tottheta.lt.0.0)) then
    wi2=1.0/wi2
    wi1=wi2*wi1
    tottheta=0.5*3.14159+tottheta
  endif
  statev(2)=wi1
  statev(3)=wi2
  statev(4)=atheta
  statev(5)=aphi
  statev(6)=apsi
  statev(7)=eps_plastic
  statev(8)=sigy1
  statev(10)=hrd
  statev(11)=wi1/wi2
  statev(12)=rotj(1,1)
  statev(13)=rotj(1,2)
  statev(14)=rotj(1,3)
  statev(15)=rotj(2,1)
  statev(16)=rotj(2,2)
  statev(17)=rotj(2,3)
  statev(18)=rotj(3,1)
  statev(19)=rotj(3,2)
  statev(20)=rotj(3,3)
  tottheta=dasin(rot(3,2))
  statev(21)=tottheta*180.0/3.14159
  statev(22)=totphi*180.0/3.14159
  statev(23)=totpsi*180.0/3.14159
  statev(24)=1.0/wi2
  statev(25)=(1.0/wi2)*wi1
  statev(26)=1.000/wi1
c----- converting ddsdde for the case of 2D analyses:

```

```

if (ntens.eq.4) then
  ddsdde(1,1)=ddsdde_mine(2,2)
  ddsdde(1,2)=ddsdde_mine(2,3)
  ddsdde(1,3)=ddsdde_mine(2,1)
  ddsdde(1,4)=ddsdde_mine(2,6)
  ddsdde(2,1)=ddsdde_mine(3,2)
  ddsdde(2,2)=ddsdde_mine(3,3)
  ddsdde(2,3)=ddsdde_mine(3,1)
  ddsdde(2,4)=ddsdde_mine(3,6)
  ddsdde(3,1)=ddsdde_mine(1,2)
  ddsdde(3,2)=ddsdde_mine(1,3)
  ddsdde(3,3)=ddsdde_mine(1,1)
  ddsdde(3,4)=ddsdde_mine(1,6)
  ddsdde(4,1)=ddsdde_mine(6,2)
  ddsdde(4,2)=ddsdde_mine(6,3)
  ddsdde(4,3)=ddsdde_mine(6,1)
  ddsdde(4,4)=ddsdde_mine(6,6)
  else
    do i=1,6
      do j=1,6
        ddsdde(i,j)=ddsdde_mine(i,j)
      enddo
    enddo
  endif
111  return
end

=====
c=====
subroutine funcd(dlam,fun,dfun)
real*8 fun,func,dlam,dfun
logical debug,neg,check,yield
common /mkdata2/yield,check,neg
common /mdebug/debug
external func

c
fun=func(dlam)
if (neg.eq..true.) then
  write(15,*)"Returning from FUNCD: Problem due to func evaluation"
  call flush(15)
  return
endif
dfun=(func(dlam+0.0001*dlam)-fun)/(0.0001*dlam)
if (dfun.eq.0.0) then
  write(15,*)"You should never see this statement: Error trapping
& incorrect in func"
  call flush(15)
  neg=.true.
endif
if (neg.eq..true.) then
  write(15,*)"Returning from FUNCD. Problem: In func during
& slope calculation"
  call flush(15)
  return
endif
if(debug.eq..true.) then
  write(15,*)"dfun",dfun,fun,func(dlam+0.0001*dlam)
endif
return
end

=====
c=====
subroutine update(dlam,ddsdde)
real*8 s(3,3),MHS(6,6),Amat(6,6),Ce(6,6)
real*8 sn(3,3),n(3,3),omega(3,3),sige(3,3),L
real*8 strainc(6),sigec(6),ddsdde(6,6),sn1(3,3)
real*8 sigma_n(6),sig_n(6),ddsdum(6,6)
real*8 f,wil,wi2,atheta,aphi,apsi,athetan,aphin,apsin
real*8 fn,wi1n,wi2n,dlam,dumm(3,3,3,3)
real*8 sc(6),nc(6),omegac(6),sigyln
real*8 mul,k1,mu2,k2,sigy1,H,dumm1(3,3,3,3)
real*8 dummy(6),a,b,c,ad,bd,cd,dummy1(3,3),dummy2(3,3)
real*8 dummy5(6),dum1,nu1,nu2,sigy0
real*8 deps(3,3),eps_plastic,dep_plas,dumd(6,6)
real*8 det,k11,dphidf,phi1,phi2,ftest
real*8 e1212,e2323,e1313,pi1212,pi2323,pi1313,bmat(6,6)
real*8 mule,k1e,mu2e,ek2e,Ce_temp(6,6)
real*8 ate,bte,dphidwi1,dphidwi2,wiltest,wi2test
real*8 dum5,dum10,y,dinc(6),R(3,3),RT(3,3)
real*8 cp,sp,ct,st,cs,ss,rot(3,3),rott(3,3)
real*8 cpn,spn,ctn,stn,csn,ssn,rotn(3,3),rotnt(3,3)
real*8 vec(3),hrc,rotj(3,3),rotjn(3,3),rota(3,3)
real*8 test(6,6),loadp(6),loading

```

```

real*8 zero(6),totstrain(6)
integer i,j,ninc,indx(6),inpt
logical path,yield,check,neg,spath,yc,debug
logical evolf,evolwi,evolti
common /controls/evolf,evolwi,evolti
common /mkmodulus/mul,k1,mu2,k2,sigy0,k11
common /mkelas/mule,kle,mu2e,ek2e
common /mkdata1/f,wil,wi2,sc,strainc,eps_plastic,sigy1,hrd
common /mkorient/cp,sp,ct,st,cs,ss,rot,rott,atheta,aphi,apsi
common /mkdata2/yield,check,neg
common /mkrot/R,RT,rotj
common /paths/spath
common /mdebug/debug

c
path=.true.
neg=.false.

c
if(debug.eq..true.) then
write(15,*)'update1'
call flush(15)
endif
c
write(16,*)'strainc',strainc
nul=0.5*(3.0*k1-2.0*mu1)/(3.0*k1+mu1)
nu2=0.5*(3.0*k2-2.0*mu2)/(3.0*k2+mu2)
c=1.000
a=c/wil
b=c/wi2
ad=a
bd=b
cd=c
if (yield.eq..false.) then
c---- The elastic predictor is the correct stress
c---- The state variables are unchanged by elastic deformations
c---- and so there is no need to update them.
path=.false.
call Meffective(a,b,c,ad,bd,cd,f,mule,kle,mu2e,ek2e,Ce,path)
path=.true.
call temmatprod(Ce,strainc,sigec)
sige(1,1)=sc(1)+sigec(1)
sige(2,2)=sc(2)+sigec(2)
sige(3,3)=sc(3)+sigec(3)
sige(1,2)=(sc(4)+sigec(4))/dsqrt(2.D0)
sige(2,3)=(sc(5)+sigec(5))/dsqrt(2.D0)
sige(3,1)=(sc(6)+sigec(6))/dsqrt(2.D0)
sige(2,1)=sige(1,2)
sige(3,2)=sige(2,3)
sige(1,3)=sige(3,1)
c---- update stress (state variables are unchanged!)
c---- Express stress in GLOBAL coordinate frame.
call matprod(rot,sige,dummy1)
call matprod(dummy1,rott,sige)
sc(1)=sige(1,1)
sc(2)=sige(2,2)
sc(3)=sige(3,3)
sc(4)=sige(1,2)*dsqrt(2.D0)
sc(5)=sige(2,3)*dsqrt(2.D0)
sc(6)=sige(3,1)*dsqrt(2.D0)
c---- calculate ddsdde
do 431 i=1,6
  do 441 j=1,6
    dumd(i,j)=Ce(i,j)
441  continue
431  continue
c---- Express ddsdde in GLOBAL coordinate frame
call mat2tensor(dumd,dumm)
call rot4order(dumm,rot,dumm1)
call ten2matrix(dumm1,Ce_temp)
c---- Expressing ddsdde in the notation of ABAQUS
do 432 i=1,3
  dumd(i,4)=Ce_temp(i,4)/dsqrt(2.D0)
  dumd(i,5)=Ce_temp(i,5)/dsqrt(2.D0)
  dumd(i,6)=Ce_temp(i,6)/dsqrt(2.D0)
432  continue
do 433 i=4,6
  dumd(i,1)=Ce_temp(i,1)/dsqrt(2.D0)
  dumd(i,2)=Ce_temp(i,2)/dsqrt(2.D0)
  dumd(i,3)=Ce_temp(i,3)/dsqrt(2.D0)
433  continue
do 434 i=4,6
  do 435 j=4,6
    dumd(i,j)=Ce_temp(i,j)/2.0
  continue
434  continue
do 436 i=1,4

```

```

do 437 j=1,4
  ddsdde(i,j)=dumd(i,j)
437  continue
436  continue
  do 438 i=1,4
    ddsdde(i,5)=dumd(i,6)
    ddsdde(i,6)=dumd(i,5)
438  continue
  do 439 i=1,4
    ddsdde(5,i)=dumd(6,i)
    ddsdde(6,i)=dumd(5,i)
439  continue
    ddsdde(5,5)=dumd(6,6)
    ddsdde(5,6)=dumd(6,5)
    ddsdde(6,5)=dumd(5,6)
    ddsdde(6,6)=dumd(5,5)
    call ludcmp(Ce_temp,6,6,indx,det)
    do 544 j=1,6
      det=det*Ce_temp(j,j)
544  continue
      if (det.lt.0.0) then
c        write(15,*)'ddsdde_elastic',a,b,c
c        write(15,*)ddsdde
c        write(15,*)'det',det
      endif
      go to 999
    endif
c----- If the material has become plastic, the microstructural variables
c need to be updated. Also the new stress has to be evaluated carefully
c since the strains are no longer completely elastic. We must obtain
c the plastic part of the strain (which is done by obtaining 'dlam'
c i.e., delta_lambda) and then that is used to update all relevant
c variables.
c----- calculate Meffective
call Meffective(a,b,c,ad,bd,cd,f,mul1,k11,mu2,k2,MHS,path)
do 100 i=1,6
  do 110 j=1,6
    MHS(i,j)=3.0*mul1*MHS(i,j)
110  continue
100  continue
c-----
c----- estimate stress
c----- STEP 1: Estimate the elastic predictor
path=.false.
call Meffective(a,b,c,ad,bd,cd,f,mule,k1e,mu2e,ek2e,Ce,path)
path=.true.
call tenmatprod(Ce,strainc,sigec)
do 201, i=1,6
  loadp(i)=sigec(i)
201  continue
  sige(1,1)=sc(1)+sigec(1)
  sige(2,2)=sc(2)+sigec(2)
  sige(3,3)=sc(3)+sigec(3)
  sige(1,2)=(sc(4)+sigec(4))/dsqrt(2.D0)
  sige(2,3)=(sc(5)+sigec(5))/dsqrt(2.D0)
  sige(3,1)=(sc(6)+sigec(6))/dsqrt(2.D0)
  sige(2,1)=sige(1,2)
  sige(3,2)=sige(2,3)
  sige(1,3)=sige(3,1)
  sigec(1)=sige(1,1)
  sigec(2)=sige(2,2)
  sigec(3)=sige(3,3)
  sigec(4)=sige(1,2)*dsqrt(2.D0)
  sigec(5)=sige(2,3)*dsqrt(2.D0)
  sigec(6)=sige(3,1)*dsqrt(2.D0)
c----- STEP 1a: Determining the stress on the yield surface
  sigma_n(1)=sc(1)
  sigma_n(2)=sc(2)
  sigma_n(3)=sc(3)
  sigma_n(4)=sc(4)
  sigma_n(5)=sc(5)
  sigma_n(6)=sc(6)
  call yieldtest(MHS,sigma_n,sigyl,f,yc,y)
  if (yc.eq..false.) then
    call yieldtest(MHS,sigec,sigyl,f,yc,y)
    if (yc.eq..true.) then
      c        this is the step where the behavior becomes plastic (the previous
      c        step was elastic)
      check=.true.
      do 127 i=1,6
        zero(i)=0.0
        totstrain(i)=strainc(i)
127      continue
        ninc=100.0

```

```

    call stre(sigma_n,sigec,zero,totstrain,sig_n,Ce,ninc)
    else
      write(15,*)"NOT PLASTIC, shouldnt have come here"
      call flush(15)
      do 130 i=1,6
        sig_n(i)=sc(i)
130      continue
      endif
    else
      do 131 i=1,6
        sig_n(i)=sc(i)
131      continue
      endif
c----- calculate N(3,3)
call temmatprod(MHS,sig_n,nc)
do 200 i=1,6
  nc(i)=nc(i)/(1.0-f)
  nc(i)=2.0*nc(i)/sigy1
  dummy(i)=nc(i)
  dummy5(i)=nc(i)
200  continue
c   write(16,*)'mhs',mhs(1,1),mhs(1,2),mhs(1,3),mhs(1,4)
c   &           ,mhs(1,5),mhs(1,6)
c   & write(16,*)'mhs2',mhs(2,1),mhs(2,2),mhs(2,3),mhs(2,4)
c   &           ,mhs(2,5),mhs(2,6)
c   write(16,*)"sign",sig_n
c   write(16,*)"nc",nc
c   write(15,*)"exit stress"
c   write(15,*)"sig_n"
n(1,1)=nc(1)
n(2,2)=nc(2)
n(3,3)=nc(3)
n(1,2)=nc(4)/dsqrt(2.D0)
n(2,1)=n(1,2)
n(2,3)=nc(5)/dsqrt(2.D0)
n(3,2)=n(2,3)
n(3,1)=nc(6)/dsqrt(2.D0)
n(1,3)=n(3,1)
c----- Test for loading/unloading
call rowcolumnprod(loadp,dummy5,loading)
do 203 i=1,6
  dummy5(i)=nc(i)
203  continue
  if (loading.le.0.0) then
    write(15,*)"loading",loading
  endif
c----- STEP 2: Remaining part of the stress
c----- STEP 2a: Calculating 'omega'
spath=.false.
call stensor(a,b,c,nul,k1,mul,dumd,pi1212,pi1313,pi2323)
if (debug.eq..true.) then
  write(15,*)"pi1212",pi1212,pi2323,pi1313
  call flush(15)
endif
e1212=pi1212-f*pi1212
e2323=pi2323-f*pi2323
e1313=pi1313-f*pi1313
spath=.true.
call Btensor(a,b,c,ad,bd,cd,f,mul,k1,mu2,k2,Bmat)
do 41 i=1,3
  do 42 j=1,6
    Bmat(i,j)=0.0
41   continue
42   continue
Bmat(4,1)=2.0*e1212*Bmat(4,1)
Bmat(4,2)=2.0*e1212*Bmat(4,2)
Bmat(4,3)=2.0*e1212*Bmat(4,3)
Bmat(4,4)=2.0*e1212*Bmat(4,4)
Bmat(4,5)=2.0*e1212*Bmat(4,5)
Bmat(4,6)=2.0*e1212*Bmat(4,6)
Bmat(5,1)=2.0*e2323*Bmat(5,1)
Bmat(5,2)=2.0*e2323*Bmat(5,2)
Bmat(5,3)=2.0*e2323*Bmat(5,3)
Bmat(5,4)=2.0*e2323*Bmat(5,4)
Bmat(5,5)=2.0*e2323*Bmat(5,5)
Bmat(5,6)=2.0*e2323*Bmat(5,6)
Bmat(6,1)=2.0*e1313*Bmat(6,1)
Bmat(6,2)=2.0*e1313*Bmat(6,2)
Bmat(6,3)=2.0*e1313*Bmat(6,3)
Bmat(6,4)=2.0*e1313*Bmat(6,4)
Bmat(6,5)=2.0*e1313*Bmat(6,5)
Bmat(6,6)=2.0*e1313*Bmat(6,6)
call Atensor(a,b,c,ad,bd,cd,f,mul,k1,mu2,k2,Amat)
do 3 i=1,3

```

```

      do 4 j=1,3
        omega(i,j)=0.0
4      continue
3      continue
      do 1 i=1,3
        omega(1,2)=-Bmat(4,i)*nc(i)+omega(1,2)
        omega(2,3)=-Bmat(5,i)*nc(i)+omega(2,3)
        omega(1,3)=-Bmat(6,i)*nc(i)+omega(1,3)
1      continue
      do 2 i=4,6
        omega(1,2)=-Bmat(4,i)*nc(i)+omega(1,2)
        omega(2,3)=-Bmat(5,i)*nc(i)+omega(2,3)
        omega(1,3)=-Bmat(6,i)*nc(i)+omega(1,3)
2      continue
        omega(2,1)=-omega(1,2)
        omega(3,2)=-omega(2,3)
        omega(3,1)=-omega(1,3)
      do 7 i=1,3
        do 8 j=1,3
          omega(i,j)=omega(i,j)/dsqrt(2.0d0)
8      continue
7      continue
      call tenmatprod(Amat,nc,dinc)
      c=1.000
      a=c/wi1
      b=c/wi2
      if (dabs(a-b).gt.0.01) then
        omega(1,2)=omega(1,2)-(a*a+b*b)*dinc(4)/(dsqrt(2.0d0)*(a*a-b*b))
      endif
      if (dabs(a-c).gt.0.01) then
        omega(1,3)=omega(1,3)-(a*a+c*c)*dinc(6)/(dsqrt(2.0d0)*(a*a-c*c))
      endif
      if (dabs(c-b).gt.0.01) then
        omega(2,3)=omega(2,3)-(b*b+c*c)*dinc(5)/(dsqrt(2.0d0)*(b*b-c*c))
      endif
      omega(2,1)=-omega(1,2)
      omega(3,2)=-omega(2,3)
      omega(3,1)=-omega(1,3)
      omegac(1)=omega(1,1)
      omegac(2)=omega(2,2)
      omegac(3)=omega(3,3)
      omegac(4)=omega(1,2)*dsqrt(2.D0)
      omegac(5)=omega(2,3)*dsqrt(2.D0)
      omegac(6)=omega(1,3)*dsqrt(2.D0)
c-----
      s(1,1)=sc(1)
      s(2,2)=sc(2)
      s(3,3)=sc(3)
      s(1,2)=sc(4)/dsqrt(2.D0)
      s(2,3)=sc(5)/dsqrt(2.D0)
      s(3,1)=sc(6)/dsqrt(2.D0)
      s(2,1)=s(1,2)
      s(3,2)=s(2,3)
      s(1,3)=s(3,1)
      call matprod(s,omega,dummy1)
      call matprod(omega,s,dummy2)
      do 300 i=1,3
        do 310 j=1,3
          sn(i,j)=dummy1(i,j)-dummy2(i,j)
310    continue
300    continue
      call tenmatprod(Ce,nc,dummy)
      sn(1,1)=sn(1,1)-dummy(1)
      sn(2,2)=sn(2,2)-dummy(2)
      sn(3,3)=sn(3,3)-dummy(3)
      sn(1,2)=sn(1,2)-dummy(4)/dsqrt(2.D0)
      sn(2,3)=sn(2,3)-dummy(5)/dsqrt(2.D0)
      sn(3,1)=sn(3,1)-dummy(6)/dsqrt(2.D0)
      sn(2,1)=sn(1,2)
      sn(3,2)=sn(2,3)
      sn(1,3)=sn(3,1)
      do 320 i=1,3
        do 330 j=1,3
          dummy1(i,j)=sn(i,j)
330    continue
320    continue
c----- STEP 3: put them together
      sn1(1,1)=sige(1,1)+dlam*sn(1,1)
      sn1(2,2)=sige(2,2)+dlam*sn(2,2)
      sn1(3,3)=sige(3,3)+dlam*sn(3,3)
      sn1(1,2)=sige(1,2)+dlam*sn(1,2)
      sn1(2,3)=sige(2,3)+dlam*sn(2,3)
      sn1(3,1)=sige(3,1)+dlam*sn(3,1)
      sn1(2,1)=sn1(1,2)

```

```

sn1(3,2)=sn1(2,3)
sn1(1,3)=sn1(3,1)
c----- These components of sn1 are now NOT in the coordinate frame
c----- coincides with the orientation of the inclusions. This is due
c----- the algorithm used (see notes for more details). The stress components
c----- are now relative to a frame which is obtained by rotating the
c----- orientation of the particles by R. So obtain the components relative
c----- to the orientation of the particles at the beginning of this
c----- increment:
call matprod(R,sn1,dummy1)
call matprod(dummy1,RT,sn1)

c----- estimate the new state variables
if (evolf.eq..true.) then
fn=f+(n(1,1)+n(2,2)+n(3,3))*(1.0-f)*dlam
else
fn=f
endif
if (inpt.eq.1) then
endif
call Atensor(a,b,c,ad,bd,cd,f,mu1,k1,mu2,k2,Amat)
dummy(1)=Amat(3,1)-Amat(1,1)
dummy(2)=Amat(3,2)-Amat(1,2)
dummy(3)=Amat(3,3)-Amat(1,3)
dummy(4)=Amat(3,4)-Amat(1,4)
dummy(5)=Amat(3,5)-Amat(1,5)
dummy(6)=Amat(3,6)-Amat(1,6)
call rowcolumnprod(dummy,dummy5,dum5)
c
write(16,*)'dummy1',dummy
c
write(16,*)'dummy5',dummy5
c
write(16,*), 'A1', Amat(3,1)
c
write(16,*), 'A1', Amat(3,2)
c
write(16,*), 'A1', Amat(3,3)
c
write(16,*), 'A1', Amat(3,4)
c
write(16,*), 'A1', Amat(3,5)
c
write(16,*), 'A1', Amat(3,6)
c
write(16,*), 'A1', Amat(1,1)
c
write(16,*), 'A1', Amat(1,2)
c
write(16,*), 'A1', Amat(1,3)
c
write(16,*), 'A1', Amat(1,4)
c
write(16,*), 'A1', Amat(1,5)
c
write(16,*), 'A1', Amat(1,6)
do 400 i=1,6
    dummy5(i)=nc(i)
400 continue
dummy(1)=Amat(3,1)-Amat(2,1)
dummy(2)=Amat(3,2)-Amat(2,2)
dummy(3)=Amat(3,3)-Amat(2,3)
dummy(4)=Amat(3,4)-Amat(2,4)
dummy(5)=Amat(3,5)-Amat(2,5)
dummy(6)=Amat(3,6)-Amat(2,6)
call rowcolumnprod(dummy,dummy5,dum10)
c
write(16,*)'dummy2',dummy
c
write(16,*)'dummy52',dummy5
c
write(16,*), 'A2', Amat(3,1)
c
write(16,*), 'A2', Amat(3,2)
c
write(16,*), 'A2', Amat(3,3)
c
write(16,*), 'A2', Amat(3,4)
c
write(16,*), 'A2', Amat(3,5)
c
write(16,*), 'A2', Amat(3,6)
c
write(16,*), 'A2', Amat(2,1)
c
write(16,*), 'A2', Amat(2,2)
c
write(16,*), 'A2', Amat(2,3)
c
write(16,*), 'A2', Amat(2,4)
c
write(16,*), 'A2', Amat(2,5)
c
write(16,*), 'A2', Amat(2,6)
if (evolwi.eq..true.) then
    wiln=wil+dlam*wil*dum5
    wi2n=wi2+dlam*wi2*dum10
c
    write(15,*)'win',wiln,wi2n
    write(15,*)'wil',wil,wi2,dum5,dum10
else
    wiln=wil
    wi2n=wi2
endif
if ((wiln.le.0.0).or.(wi2n.le.0.0)) then
    write(15,*)'Aspects have become negative'
    call flush(15)
    neg=.true.
    return
endif
c----- estimating new orientations
if (evolti.eq..true.) then
    athetan=atheta-(omega(2,3)*cp+omega(1,3)*sp)*dlam

```

```

if (dabs(wi2n-1.0).lt.0.01) then
  athetan=0.0
  endif
  if (st.ne.0.0) then
    aphi=aphi-((omega(2,3)*ss/st)-omega(1,3)*cs/st)*dlam
    apsi=apsi+(-omega(1,2)+(ct/st)*(omega(2,3)*ss-omega(1,3)*cs))*dlam
  & else
    apsin=0.0
    aphi=0.0
  endif
call matprod(R,rotj,rotjn)
else
  aphi=aphi
  apsi=apsi
  athetan=atheta
do 27 i=1,3
  do 28 j=1,3
    rotjn(i,j)=rotj(i,j)
    continue
    continue
  endif
  ctn=dcos(athetan)
  stn=dsin(athetan)
  cpn=dcos(aphi)
  csn=dcos(apsin)
  spn=dsin(aphi)
  ssn=dsin(apsin)
  rota(1,1)=csn*cpn-ssn*ctn*spn
  rota(1,2)=-csn*spn-ssn*ctn*cpn
  rota(1,3)=ssn*stn
  rota(2,1)=ssn*cpn+csn*ctn*spn
  rota(2,2)=-ssn*spn+csn*ctn*cpn
  rota(2,3)=-csn*stn
  rota(3,1)=stn*spn
  rota(3,2)=stn*cpn
  rota(3,3)=ctn
call matprod(rota,rotjn,rotn)
  do 77 i=1,3
    do 88 j=1,3
      rotnt(i,j)=rotn(j,i)
    continue
    continue
 88
 77
c-----
c----- update stress and state variables:
c     The stress must now be expressed w.r.t the new orientation of the
c     particles so that ddsdde can be calculated.
c     First we take it back w.r.t the GLOBAL axes:
call matprod(rot,sn1,dummy)
call matprod(dummy,rott,sn1)
c     and then express it in w.r.t the new orientation of the particles.
call matprod(rotnt,sn1,dummy)
call matprod(dummy,rotn,sn1)
sc(1)=sn1(1,1)
sc(2)=sn1(2,2)
sc(3)=sn1(3,3)
sc(4)=sn1(1,2)*dsqrt(2.D0)
sc(5)=sn1(2,3)*dsqrt(2.D0)
sc(6)=sn1(3,1)*dsqrt(2.D0)
f=fn
wi1=wi1n
wi2=wi2n
c=1.000
a=c/wi1
b=c/wi2
ad=a
bd=b
cd=c
do 37 i=1,3
do 38 j=1,3
  rotj(i,j)=rotjn(i,j)
  continue
38
37
  continue
  atheta=athetan
  aphi=aphi
  apsi=apsin
  do 707 i=1,3
    do 808 j=1,3
      rot(i,j)=rotn(i,j)
      rott(i,j)=rotnt(i,j)
    continue
 808
 707
  continue
c----- updating sig_yield
  do 501 i=1,3

```

```

      do 502 j=1,3
        deps(i,j)=dlam*n(i,j)
502    continue
501    continue
duml=(deps(1,1)+deps(2,2)+deps(3,3))/3.0
      do 503 i=1,3
        deps(i,i)=deps(i,i)-duml
503    continue
      dep_plas=deps(1,1)**2+deps(2,2)**2+deps(3,3)**2
      dep_plas=dep_plas+2.0*(deps(1,2)**2+deps(2,3)**2+deps(3,1)**2)
      dep_plas=(2.0/3.0)*dep_plas
      eps_plastic=eps_plastic+dsqrt(dep_plas)
      sigyln=sigy0*((1.0+eps_plastic)**(1.0/3.0))
C      sigyl=sigyln
      sigyln=sigyl
C-----
      call Meffective(a,b,c,ad,bd,cd,f,mul,k11,mu2,k2,MHS,path)
      do 391 i=1,6
        do 392 j=1,6
          MHS(i,j)=3.0*mul*MHS(i,j)
392    continue
391    continue
      call yieldtest(MHS,sc,sigyl,f,yc,y)
C
C----- CALCULATE ddsdde
C----- calculate N
      do 399 i=1,6
        dummy5(i)=sc(i)
399    continue
      call tenmatprod(MHS,dummy5,nc)
      do 401 i=1,6
        nc(i)=nc(i)/(1.0-f)
        nc(i)=2.0*nc(i)/sigyl
401    continue
      path=.false.
      call Meffective(a,b,c,ad,bd,cd,f,mule,k1e,mu2e,ek2e,Ce,path)
      path=.true.
      do 470 i=1,6
        do 471 j=1,6
          test(i,j)=Ce(i,j)
471    continue
470    continue
      call ludcmp(test,6,6,indx,det)
      do 443 j=1,6
        det=det*test(j,j)
443    continue
        if (det.lt.0.0) then
          write(15,*)'Ce is wrong during plastic step'
          call flush(15)
        endif
        do 410 i=1,6
          dummy5(i)=nc(i)
410    continue
        call tenmatprod(Ce,dummy5,dummy)
        do 420 i=1,6
          dummy5(i)=nc(i)
420    continue
        call rowcolumnprod(dummy,dummy5,L)
C----- calculating H
C----- step A -- calculating dphi/df
        H=0.0
        path=.true.
        if (evolf.eq..true.) then
          call Meffective(a,b,c,ad,bd,cd,f,mul,k11,mu2,k2,MHS,path)
          do 1001 i=1,6
            do 1002 j=1,6
              MHS(i,j)=3.0*mul*MHS(i,j)
1002        continue
1001        continue
          call yieldtest(MHS,sc,sigyl,f,yc,phi1)
          ftest=f+0.001*f
          call Meffective(a,b,c,ad,bd,cd,ftest,mul,k11,mu2,k2,MHS,path)
          do 1003 i=1,6
            do 1004 j=1,6
              MHS(i,j)=3.0*mul*MHS(i,j)
1004        continue
1003        continue
          call yieldtest(MHS,sc,sigyl,ftest,yc,phi2)
          dphidf=(phi2-phi1)/(ftest-f)
          H=0.0
          H=-dphidf*(1.0-f)*(nc(1)+nc(2)+nc(3))
        endif
C----- step B -- calculating dphi/dwil
        if (evolwi.eq..true.) then

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```

path=.true.
call Meffective(a,b,c,ad,bd,cd,f,mul,k11,mu2,k2,MHS,path)
do 2001 i=1,6
  do 2002 j=1,6
    MHS(i,j)=3.0*mul*MHS(i,j)
2002      continue
2001      continue
      call yieldtest(MHS,sc,sigyl,f,yc,phi1)
      wiltest=wil+0.001*wil
      ate=c/wiltest
      call Meffective(ate,b,c,ate,b,c,f,mul,k11,mu2,k2,
                      MHS,path)
&      do 2003 i=1,6
        do 2004 j=1,6
          MHS(i,j)=3.0*mul*MHS(i,j)
2004      continue
2003      continue
      call yieldtest(MHS,sc,sigyl,f,yc,phi2)
      dphidwil=(phi2-phi1)/(wiltest-wil)
      H=H-dphidwil*wil*dum5
      endif
c----- step C -- calculating dphi/dwi2
if (evolwi.eq..true.) then
  path=.true.
  call Meffective(a,b,c,ad,bd,cd,f,mul,k11,mu2,k2,MHS,path)
  do 3001 i=1,6
    do 3002 j=1,6
      MHS(i,j)=3.0*mul*MHS(i,j)
3002      continue
3001      continue
      call yieldtest(MHS,sc,sigyl,f,yc,phi1)
      wi2test=wi2+0.001*wi2
      bte=c/wi2test
      call Meffective(a,bte,c,a,bte,c,f,mul,k11,mu2,k2,
                      MHS,path)
&      do 3003 i=1,6
        do 3004 j=1,6
          MHS(i,j)=3.0*mul*MHS(i,j)
3004      continue
3003      continue
      call yieldtest(MHS,sc,sigyl,f,yc,phi2)
      dphidwil2=(phi2-phi1)/(wi2test-wi2)
      H=H-dphidwil2*wi2*dum10
      endif
      if(debug.eq..true.) then
        write(15,*) 'update8'
        call flush(15)
      endif
      hrd=H
c-----
c      L=L+H
c      write(15,*) 'L',L,'H',H
c      call flush(15)
c      if (L.lt.0.0) then
c        write(15,*) 'L is negative'
c        call flush(15)
c      endif
c-----
s(1,1)=sc(1)
s(2,2)=sc(2)
s(3,3)=sc(3)
s(1,2)=sc(4)/dsqrt(2.D0)
s(2,3)=sc(5)/dsqrt(2.D0)
s(3,1)=sc(6)/dsqrt(2.D0)
s(2,1)=s(1,2)
s(3,2)=s(2,3)
s(1,3)=s(3,1)
do 450 i=1,6
  dummy5(i)=nc(i)
450      continue
      call tenmatprod(Ce,dummy5,dummy)
      call columnrowprod(dummy,dummy,ddsdde)
      do 430 i=1,6
        do 440 j=1,6
          ddsdde(i,j)=Ce(i,j)-ddsdde(i,j)/L
440      continue
430      continue
c-----
      do 111 i=1,6
        do 112 j=1,6
          test(i,j)=ddsdde(i,j)
112      continue
111      continue
          call ludcmp(test,6,6,indx,det)

```

```

do 113 j=1,6
  det=det*test(j,j)
113 continue
  if (det.lt.0.0) then
    write(15,*)'det1',det
    call flush(15)
  endif
  call matprod(s,omega,dummy1)
  call matprod(omega,s,dummy2)
  do 421 i=1,3
    do 422 j=1,3
      dummy1(i,j)=dummy1(i,j)-dummy2(i,j)
      dummy1(i,j)=0.0
422 continue
421 continue
  dummy5(1)=dummy1(1,1)
  dummy5(2)=dummy1(2,2)
  dummy5(3)=dummy1(3,3)
  dummy5(4)=dummy1(1,2)*dsqrt(2.D0)
  dummy5(5)=dummy1(2,3)*dsqrt(2.D0)
  dummy5(6)=dummy1(3,1)*dsqrt(2.D0)
  call columnrowprod(dummy5,dummy,ddsdum)
  if (evolf.eq..true.) then
    do 4431 i=1,6
      do 4432 j=1,6
        ddsdde(i,j)=ddsdde(i,j)+ddsdum(i,j)/L
4432 continue
4431 continue
      endif
c-----Express components of ddsdde w.r.t fixed GLOBAL axes.
      call mat2tensor(ddsdde,dumm)
      call rot4order(dumm,rotn,dumm1)
      call ten2matrix(dumm1,ddsdde)
      do 570 i=1,6
        do 571 j=1,6
          dumd(i,j)=ddsdde(i,j)
571 continue
570 continue
      call ludcmp(dumd,6,6,indx,det)
      do 543 j=1,6
        det=det*dumd(j,j)
543 continue
      if (det.lt.0.0) then
        c   write(15,*)'abc',a,b,c
        c   write(15,*)ddsdde
        c   write(15,*)'
        c   write(15,*)'Ce'
        c   write(15,*)Ce
        c   write(15,*)'det',det
      endif
c----- Express stress components w.r.t GLOBAL axes.
      if (evolti.eq..true.) then
        call matprod(rotn,s,dummy1)
        call matprod(dummy1,rotnt,s)
      endif
        sc(1)=s(1,1)
        sc(2)=s(2,2)
        sc(3)=s(3,3)
        sc(4)=s(1,2)*dsqrt(2.D0)
        sc(5)=s(2,3)*dsqrt(2.D0)
        sc(6)=s(3,1)*dsqrt(2.D0)
c----- If the constitutive equation is written in terms of the
c Jaumann rate of the Cauchy stress, then ddsdde will be
c unsymmetric. The additional quantity that appears in ddsdde
c is added below.
c   write(15,*)'dds11',ddsdde(1,1),s(1,1)
c   write(15,*)'dds22',ddsdde(2,2),s(2,2)
c   write(15,*)'dds33',ddsdde(3,3),s(3,3)
c   write(15,*)'dds44',ddsdde(4,1),sc(4)
c   write(15,*)'dds55',ddsdde(5,1),sc(5)
c   write(15,*)'dds66',ddsdde(6,1),sc(6)
c   call flush(15)
c   ddsdde(1,1)=ddsdde(1,1)+s(1,1)
c   ddsdde(1,2)=ddsdde(1,2)+s(1,1)
c   ddsdde(1,3)=ddsdde(1,3)+s(1,1)
c   ddsdde(2,1)=ddsdde(2,1)+s(2,2)
c   ddsdde(2,2)=ddsdde(2,2)+s(2,2)
c   ddsdde(2,3)=ddsdde(2,3)+s(2,2)
c   ddsdde(3,1)=ddsdde(3,1)+s(3,3)
c   ddsdde(3,2)=ddsdde(3,2)+s(3,3)
c   ddsdde(3,3)=ddsdde(3,3)+s(3,3)
c   ddsdde(4,1)=ddsdde(4,1)+sc(4)
c   ddsdde(4,2)=ddsdde(4,2)+sc(4)
c   ddsdde(4,3)=ddsdde(4,3)+sc(4)

```

```

c      ddsdde(5,1)=ddsdde(5,1)+sc(5)
c      ddsdde(5,2)=ddsdde(5,2)+sc(5)
c      ddsdde(5,3)=ddsdde(5,3)+sc(5)
c      ddsdde(6,1)=ddsdde(6,1)+sc(6)
c      ddsdde(6,2)=ddsdde(6,2)+sc(6)
c      ddsdde(6,3)=ddsdde(6,3)+sc(6)
C---- Interchange components of ddsdde here (since our notation for
c stress and strain are different from what they use).
c      do 477 i=1,3
c         do 478 j=4,6
c            ddsdde(i,j)=ddsdde(i,j)/dsqrt(2.D0)
478      continue
477      continue
do 473 i=4,6
  do 474 j=1,3
    ddsdde(i,j)=ddsdde(i,j)/dsqrt(2.D0)
474      continue
473      continue
do 475 i=4,6
  do 476 j=4,6
    ddsdde(i,j)=ddsdde(i,j)/(2.D0)
476      continue
475      continue
do 530 i=1,6
  do 531 j=1,6
    dumd(i,j)=ddsdde(i,j)
531      continue
530      continue
do 538 i=1,4
  ddsdde(i,5)=dumd(i,6)
  ddsdde(i,6)=dumd(i,5)
538      continue
do 539 i=1,4
  ddsdde(5,i)=dumd(6,i)
  ddsdde(6,i)=dumd(5,i)
539      continue
  ddsdde(5,5)=dumd(6,6)
  ddsdde(5,6)=dumd(6,5)
  ddsdde(6,5)=dumd(5,6)
  ddsdde(6,6)=dumd(5,5)
c---- The above is the final ddsdde
do 541 i=1,6
  do 542 j=1,6
    dumd(i,j)=ddsdde(i,j)
542      continue
541      continue
if(debug.eq..true.) then
write(15,*)'update10'
call flush(15)
endif
999  return
end
=====

```

```

subroutine stre(ss,sse,p,q,estimate,Ce,ninc)
real*8 MHS(6,6)
real*8 p(6),q(6),r(6),eps_plastic,Ce(6,6)
real*8 mul,k1,mu2,k2,sigy1,f,wi1,wi2,sc(6),strainc(6)
real*8 a,b,c,ad,bd,cd,sigy0,k11,y,hrd,ss(6),sse(6),estimate(6)
integer ninc,i,j,ic
logical path,check,yield,neg,yc,debug
logical evolf,evolwi,evolti
common /controls/evolf,evolwi,evolti
common /mkmodulus/mul,k1,mu2,k2,sigy0,k11
common /mkdata1/f,wi1,wi2,sc,strainc,eps_plastic,sigy1,hrd
common /mkdata2/yield,check,neg
common /mdebug/debug
path=.true.
c=1.000
a=c/wi1
b=c/wi2
ad=a
bd=b
cd=c
call Meffective(a,b,c,ad,bd,cd,f,mul,k11,mu2,k2,MHS,path)
do 1 i=1,6
  do 2 j=1,6
    MHS(i,j)=3.0*mul*MHS(i,j)
  continue
1      continue
  if (check.eq..true.) then
    call yieldtest(MHS,ss,sigy1,f,yc,y)
    if (yc.eq..true.) then
      write(15,*)'WARNING1 IN STRE',y

```

```

        stop
      endif
      call yieldtest(MHS,sse,sigyl,f,yc,y)
      if (yc.eq..false.) then
        write(15,*) 'WARNING2 IN STRE'
        stop
      endif
    endif
  do 100 ic=i,ninc
    do 10 i=1,6
      r(i)=0.5*(p(i)+q(i))
10     continue
    call temmatprod(Ce,r,estimate)
  do 11 i=1,6
    estimate(i)=estimate(i)+ss(i)
11     continue
    call yieldtest(MHS,estimate,sigyl,f,yc,y)
cwrite(15,*)'est in stre',y
    if ((yc.eq..true.).and.(y.lt.1.0d-10))then
      return
    else
      if (yc.eq..false.) then
        do 20 i=1,6
          p(i)=r(i)
20     continue
      else
        do 30 i=1,6
          q(i)=r(i)
30     continue
      endif
    endif
100   continue
    write(15,*)'problem in stre'
    stop
    return
  end
C=====
c----- This is used to decompose the F tensor.
  subroutine decompose(F,R,U,C,D)
  real*8 F(3,3),R(3,3),FT(3,3),C(3,3)
  real*8 D(3),V(3,3),U(3,3)
  integer n,np,nrot,i,j
  logical debug
  common /mdebug/debug
    do 10 i=1,3
      do 20 j=1,3
        FT(i,j)=F(j,i)
20    continue
10    continue
    call matprod(FT,F,C)
    n=3
    np=3
    call jacobi(C,n,np,D,V,nrot)
    do 30 i=1,3
      do 40 j=1,3
        C(i,j)=0.0
        U(i,j)=0.0
40    continue
30    continue
    do 50 i=1,3
      do 60 j=1,3
        FT(i,j)=V(i,1)*V(j,1)
        U(i,j)=FT(i,j)*dlog(dsqrt(d(1)))
        C(i,j)=FT(i,j)/dsqrt(d(1))
50    continue
    continue
    do 70 i=1,3
      do 80 j=1,3
        FT(i,j)=V(i,2)*V(j,2)
        U(i,j)=(FT(i,j)*dlog(dsqrt(d(2))))+U(i,j)
        C(i,j)=(FT(i,j)/dsqrt(d(2)))+C(i,j)
80    continue
70    continue
    do 90 i=1,3
      do 100 j=1,3
        FT(i,j)=V(i,3)*V(j,3)
        U(i,j)=(FT(i,j)*dlog(dsqrt(d(3))))+U(i,j)
        C(i,j)=(FT(i,j)/dsqrt(d(3)))+C(i,j)
100   continue
90   continue
    call matprod(F,C,R)
    call matprod(R,V,C)
    C(1,1)=C(1,1)/dsqrt(C(1,1)**2+C(2,1)**2+C(3,1)**2)

```

```

C(2,1)=C(2,1)/dsqrt(C(1,1)**2+C(2,1)**2+C(3,1)**2)
C(3,1)=C(3,1)/dsqrt(C(1,1)**2+C(2,1)**2+C(3,1)**2)
C(1,2)=C(1,2)/dsqrt(C(1,2)**2+C(2,2)**2+C(3,2)**2)
C(2,2)=C(2,2)/dsqrt(C(1,2)**2+C(2,2)**2+C(3,2)**2)
C(3,2)=C(3,2)/dsqrt(C(1,2)**2+C(2,2)**2+C(3,2)**2)
C(1,3)=C(1,3)/dsqrt(C(1,3)**2+C(2,3)**2+C(3,3)**2)
C(2,3)=C(2,3)/dsqrt(C(1,3)**2+C(2,3)**2+C(3,3)**2)
C(3,3)=C(3,3)/dsqrt(C(1,3)**2+C(2,3)**2+C(3,3)**2)
    return
end

c----- This is used to decompose the F tensor.
subroutine decompose1(F,R,U)
real*8 F(3,3),R(3,3),FT(3,3),C(3,3)
real*8 D(3),V(3,3),U(3,3),Uinv(3,3)
integer n,np,nrot,i,j
logical debug
common /mdebug/debug
do 10 i=1,3
do 20 j=1,3
    FT(i,j)=F(j,i)
    continue
    continue
call matprod(FT,F,C)
n=3
np=3
call jacobi(C,n,np,D,V,nrot)
do 30 i=1,3
do 40 j=1,3
    C(i,j)=0.0
    continue
    continue
do 50 i=1,3
do 60 j=1,3
    FT(i,j)=V(i,1)*V(j,1)
    U(i,j)=FT(i,j)*(dsqrt(d(1)))
    C(i,j)=FT(i,j)/dsqrt(d(1))
    continue
    continue
do 70 i=1,3
do 80 j=1,3
    FT(i,j)=V(i,2)*V(j,2)
    U(i,j)=(FT(i,j)*(dsqrt(d(2))))+U(i,j)
    C(i,j)=(FT(i,j)/dsqrt(d(2)))+C(i,j)
    continue
    continue
do 90 i=1,3
do 100 j=1,3
    FT(i,j)=V(i,3)*V(j,3)
    U(i,j)=(FT(i,j)*(dsqrt(d(3))))+U(i,j)
    C(i,j)=(FT(i,j)/dsqrt(d(3)))+C(i,j)
    continue
    continue
do 110 i=1,3
do 120 j=1,3
    V(i,j)=U(i,j)
    continue
    continue
call inverse3x3(V,Uinv)
call matprod(F,Uinv,R)
return
end

c----- This is a routine to multiply 2nd order tensors (3x3 matrices)
subroutine matprod(p,q,r)
real*8 p(3,3),q(3,3),r(3,3)
integer i,j,k
do 10 i=1,3
do 11 j=1,3
    r(i,j)=0.0
    continue
    continue
do 12 i=1,3
do 13 j=1,3
do 14 k=1,3
    r(i,j)=r(i,j)+p(i,k)*q(k,j)
    continue
    continue
    continue
return
end

```

```

SUBROUTINE JACOBI(A,N,NP,D,V,NROT)
implicit double precision (a-h, o-z)
integer nmax
PARAMETER (NMAX=100)
real*8 A(NP,NP),D(NP),V(NP,NP),B(NMAX),Z(NMAX)
integer ip,iq,i,n,np,nrot,j
DO 12 IP=1,N
    DO 11 IQ=1,N
        V(IP,IQ)=0.
11    CONTINUE
        V(IP,IP)=1.
12    CONTINUE
    DO 13 IP=1,N
        B(IP)=A(IP,IP)
        D(IP)=B(IP)
        Z(IP)=0.
13    CONTINUE
NROT=0
DO 24 I=1,50
    SM=0.
    DO 15 IP=1,N-1
        DO 14 IQ=IP+1,N
            SM=SM+DABS(A(IP,IQ))
14    CONTINUE
15    CONTINUE
    IF(SM.EQ.0.)RETURN
    IF(I.LT.4)THEN
        TRESH=0.2*SM/N**2
    ELSE
        TRESH=0.
    ENDIF
    DO 22 IP=1,N-1
        DO 21 IQ=IP+1,N
            G=100.*DABS(A(IP,IQ))
            IF((I.GT.4).AND.(DABS(D(IP))+G.EQ.DABS(D(IP)))
*               .AND.(DABS(D(IQ))+G.EQ.DABS(D(IQ))))THEN
                A(IP,IQ)=0.
            ELSE IF(DABS(A(IP,IQ)).GT.TRESH)THEN
                H=D(IQ)-D(IP)
                IF(DABS(H)+G.EQ.DABS(H))THEN
                    T=A(IP,IQ)/H
                ELSE
                    THETA=0.5*H/A(IP,IQ)
                    T=1./(DABS(THETA)+DSQRT(1.D0+THETA**2))
                    IF(THETA.LT.0.)T=-T
                ENDIF
                C=1./DSQRT(1.D0+T**2)
                S=T*C
                TAU=S/(1.+C)
                H=T*A(IP,IQ)
                Z(IP)=Z(IP)-H
                Z(IQ)=Z(IQ)+H
                D(IP)=D(IP)-H
                D(IQ)=D(IQ)+H
                A(IP,IQ)=0.
                DO 16 J=1,IP-1
                    G=A(J,IP)
                    H=A(J,IQ)
                    A(J,IP)=G-S*(H+G*TAU)
                    A(J,IQ)=H+S*(G-H*TAU)
16            CONTINUE
                DO 17 J=IP+1,IQ-1
                    G=A(IP,J)
                    H=A(J,IQ)
                    A(IP,J)=G-S*(H+G*TAU)
                    A(J,IQ)=H+S*(G-H*TAU)
17            CONTINUE
                DO 18 J=IQ+1,N
                    G=A(IP,J)
                    H=A(IQ,J)
                    A(IP,J)=G-S*(H+G*TAU)
                    A(IQ,J)=H+S*(G-H*TAU)
18            CONTINUE
                DO 19 J=1,N
                    G=V(J,IP)
                    H=V(J,IQ)
                    V(J,IP)=G-S*(H+G*TAU)
                    V(J,IQ)=H+S*(G-H*TAU)
19            CONTINUE
                    NROT=NROT+1
                ENDIF
21            CONTINUE
22            CONTINUE
        DO 23 IP=1,N

```

```

      B(IP)=B(IP)+Z(IP)
      D(IP)=B(IP)
      Z(IP)=0.
23   CONTINUE
24   CONTINUE
PAUSE '50 iterations should never happen'
RETURN
END

C----This is to calculate the A tensor
subroutine Atensor(a,b,c,ad,bd,cd,c2,mu1,k1,mu2,k2,Amat)
real*8 Amat(6,6),L1(6,6),L2(6,6),Si(6,6)
real*8 M1(6,6),mu1,mu2,k1,k2,nu1,nu2
real*8 a,b,c,ad,bd,cd,c1,c2
real*8 d(6,6),d1(6,6),d2(6,6),pi1212,pi2323,pi1313
integer i,j
logical debug,spath
common /paths/spath
common /mdebug/debug
spath=true.
nu1=0.5*(3.0*k1-2.0*mu1)/(3.0*k1+mu1)
nu2=0.5*(3.0*k2-2.0*mu2)/(3.0*k2+mu2)
c1=1.0-c2
if(debug.eq..true.) then
write(15,*)'Aten1'
call flush(15)
endif
c Initialize the modulus tensors
do 10 i=1,6
  do 20 j=1,6
    L1(i,j)=0.0
    L2(i,j)=0.0
    d(i,j)=0.0
20  continue
10  continue
c Obtain the (6x6) modulus tensors, L1 and L2
L1(1,1)=k1+(4.0/3.0)*mu1
L1(2,2)=k1+(4.0/3.0)*mu1
L1(3,3)=k1+(4.0/3.0)*mu1
L1(1,2)=k1-(2.0/3.0)*mu1
L1(2,1)=k1-(2.0/3.0)*mu1
L1(2,3)=k1-(2.0/3.0)*mu1
L1(3,2)=k1-(2.0/3.0)*mu1
L1(3,1)=k1-(2.0/3.0)*mu1
L1(1,3)=k1-(2.0/3.0)*mu1
L1(4,4)=2.0*mu1
L1(5,5)=2.0*mu1
L1(6,6)=2.0*mu1
L2(1,1)=k2+(4.0/3.0)*mu2
L2(2,2)=k2+(4.0/3.0)*mu2
L2(3,3)=k2+(4.0/3.0)*mu2
L2(1,2)=k2-(2.0/3.0)*mu2
L2(2,1)=k2-(2.0/3.0)*mu2
L2(2,3)=k2-(2.0/3.0)*mu2
L2(3,2)=k2-(2.0/3.0)*mu2
L2(3,1)=k2-(2.0/3.0)*mu2
L2(1,3)=k2-(2.0/3.0)*mu2
L2(4,4)=2.0*mu2
L2(5,5)=2.0*mu2
L2(6,6)=2.0*mu2
c Begin calculating A tensor
if(debug.eq..true.) then
write(15,*)'Aten2'
call flush(15)
endif
call inverse(L1,M1)
call tenprod(M1,L2,d)
do 30 i=1,6
  d(i,i)=d(i,i)-1.0
30  continue
do 31 i=1,6
  do 32 j=1,6
    d1(i,j)=0.0
    d2(i,j)=0.0
32  continue
31  continue
c calculate S tensors
if(debug.eq..true.) then
write(15,*)'Aten3'
call flush(15)
endif
call stensor(a,b,c,nu1,k1,mu1,Si,pi1212,pi1313,pi2323)
if(debug.eq..true.) then

```

```

write(15,'Aten4'
call flush(15)
endif
do 60 i=1,6
  do 70 j=1,6
    d1(i,j)=Si(i,j)-c2*Si(i,j)
  continue
continue
call tenprod(d1,d,d2)
do 80 i=1,6
  d2(i,i)=d2(i,i)+1.0
continue
if(debug.eq..true.) then
write(15,'Aten5',d2
call flush(15)
endif
call inverse(d2,Amat)
if(debug.eq..true.) then
write(15,'Aten6', Amat
call flush(15)
endif
return
end

```

```

subroutine columnrowprod(a,b,c)
real*8 a(6),b(6),c(6,6)
integer i,j
do 10 i=1,6
  do 20 j=1,6
    c(i,j)=a(i)*b(j)
20 continue
10 continue
return
end

```

C----This is to calculate the effective modulus of the composite.

```

subroutine Meffective(a,b,c,ad,bd,cd,c2,mu1,k1,mu2,k2,MHS,path)
real*8 LHS(6,6),L1(6,6),L2(6,6),Si(6,6),MHS(6,6)
real*8 M1(6,6),mu1,mu2,k1,k2,nu1,nu2
real*8 a,b,c,ad,bd,cd,c1,c2
real*8 d(6,6),d1(6,6),pi1212,pi2323,pi1313
integer i,j
logical path,spath,debug
common /paths/spath
common /mdebug/debug
spath=.true.
if(debug.eq..true.) then
  write(15,'Meff1'
  call flush(15)
endif
nu1=0.5*(3.0*k1-2.0*mu1)/(3.0*k1+mu1)
nu2=0.5*(3.0*k2-2.0*mu2)/(3.0*k2+mu2)
c1=1.0-c2
c Initialize the modulus tensors
do 10 i=1,6
  do 20 j=1,6
    L1(i,j)=0.0
    L2(i,j)=0.0
20 continue
10 continue
c Obtain the (6x6) modulus tensors, L1 and L2
L1(1,1)=k1+(4.0/3.0)*mu1
L1(2,2)=k1+(4.0/3.0)*mu1
L1(3,3)=k1+(4.0/3.0)*mu1
L1(1,2)=k1-(2.0/3.0)*mu1
L1(2,1)=k1-(2.0/3.0)*mu1
L1(2,3)=k1-(2.0/3.0)*mu1
L1(3,2)=k1-(2.0/3.0)*mu1
L1(3,1)=k1-(2.0/3.0)*mu1
L1(1,3)=k1-(2.0/3.0)*mu1
L1(4,4)=2.0*mu1
L1(5,5)=2.0*mu1
L1(6,6)=2.0*mu1
L2(1,1)=k2+(4.0/3.0)*mu2
L2(2,2)=k2+(4.0/3.0)*mu2
L2(3,3)=k2+(4.0/3.0)*mu2
L2(1,2)=k2-(2.0/3.0)*mu2
L2(2,1)=k2-(2.0/3.0)*mu2
L2(2,3)=k2-(2.0/3.0)*mu2
L2(3,2)=k2-(2.0/3.0)*mu2
L2(3,1)=k2-(2.0/3.0)*mu2
L2(1,3)=k2-(2.0/3.0)*mu2

```

```

L2(4,4)=2.0*mu2
L2(5,5)=2.0*mu2
L2(6,6)=2.0*mu2
c Begin calculating LHS
do 21 i=1,6
  do 22 j=1,6
    d1(i,j)=L1(i,j)
  continue
21 continue
if(debug.eq..true.) then
  write(15,'*')'Meff2'
  call flush(15)
endif
call inverse(d1,M1)
call tenprod(M1,L2,d)
if(debug.eq..true.) then
  write(15,'*')'Meff3'
  call flush(15)
endif
do 30 i=1,6
  d(i,i)=d(i,i)-1.0
30 continue
do 31 i=1,6
  do 32 j=1,6
    d1(i,j)=0.0
32 continue
31 continue
call inverse(d,d1)
if(debug.eq..true.) then
  write(15,'*')'Meff4'
  call flush(15)
endif
c calculate S tensors
if(debug.eq..true.) then
  write(15,'*')'Meff5',a,b,c
  call flush(15)
endif
call stensor(a,b,c,nul,k1,mul,Si,pi1212,pi1313,pi2323)
if(debug.eq..true.) then
  write(15,'*')'Meff6'
  call flush(15)
endif
if(debug.eq..true.) then
  write(15,'*')'Meff6a'
  call flush(15)
endif
do 40 i=1,6
  do 50 j=1,6
    d(i,j)=0.0
50 continue
40 continue
if(debug.eq..true.) then
  write(15,'*')'Meff6a_1',Si
  call flush(15)
endif
do 60 i=1,6
  do 70 j=1,6
    if(debug.eq..true.) then
      write(15,'*')'j=',j,'  i=',i,':',Si(i,j)
      call flush(15)
    endif
    d(i,j)=Si(i,j)-c2*Si(i,j)
70 continue
60 continue
if(debug.eq..true.) then
  write(15,'*')'Meff6b'
  call flush(15)
endif
do 80 i=1,6
  do 90 j=1,6
    d(i,j)=d1(i,j)+d(i,j)
90 continue
80 continue
if(debug.eq..true.) then
  write(15,'*')'Meff6c'
  call flush(15)
endif
do 100 i=1,6
  do 110 j=1,6
    d1(i,j)=0.0
110 continue
100 continue
if(debug.eq..true.) then
  write(15,'*')'Meff7'

```

```

    call flush(15)
  endif
  call inverse(d,d1)
  if(debug.eq..true.) then
    write(15,'*') 'Meff7a'
    call flush(15)
  endif
  do 120 i=1,6
    do 130 j=1,6
      d(i,j)=c2*d1(i,j)
130  continue
120  continue
  do 140 i=1,6
    d(i,i)=d(i,i)+1.0
140  continue
  do 150 i=1,6
    do 160 j=1,6
      d1(i,j)=0.0
160  continue
150  continue
  call tenprod(L1,d,LHS)
  do 161 i=1,6
    do 162 j=1,6
      d(i,j)=0.0
      d(i,j)=LHS(i,j)
162  continue
161  continue
  call inverse(d,MHS)
  if (path.eq..false.) then
    do 170 i=1,6
      do 180 j=1,6
        MHS(i,j)=LHS(i,j)
180  continue
170  continue
  endif
c----- symmetrize M to avoid small numerical variations
  do 190 i=1,6
    do 200 j=1,6
      M1(i,j)=MHS(i,j)
200  continue
190  continue
  do 210 i=1,6
    do 220 j=1,6
      MHS(i,j)=0.5*(M1(i,j)+M1(j,i))
220  continue
210  continue
  if(debug.eq..true.) then
    write(15,'*') 'Meff9'
    call flush(15)
  endif
  return
end
```

```

=====
C----- This is to evaluate the S tensor for an ellipsoidal inclusion.
subroutine stensor(aold,bold,cold,nu,k1,mul,s,p1212,p1313,p2323)
  real*8 ia,ib,ic,iaa,ibb,icc,iab,ibc,ica,iac,icb,iba
  real*8 a,b,c,p,e12
  real*8 ff,e
  real*8 s1111,s2222,s3333,s1122,s1133,s2233,s2211,s3311,s3322
  real*8 s1212,s1313,s2323
  real*8 q,r,nu,k1,mul
  real*8 x,qqc,qqc2,aa,bb
  real*8 s(6,6)
  real*8 a1,b1,c1,s1(6,6),aold,bold,cold
  real*8 p1212,p1313,p2323,pp1212,pp1313,pp2323
  real*8 p1221,p1331,p2332,pp1221,pp1331,pp2332
  real*8 p2112,p3113,p3223,pp2112,pp3113,pp3223
  real*8 p2121,p3131,p3232,pp2121,pp3131,pp3232
  integer ip,i,j
  logical spath,debug
  common /paths/spath
  common /mdebug/debug
  p=3.14159265358979
  p1212=0.0
  p1313=0.0
  p2323=0.0
c   p=3.14159265
  if (dabs(aold-1.D0).lt.0.001) then
    a=1.D0
    else
      a=aold
    endif
```

```

if (dabs(bold-1.D0).lt.0.001) then
  b=1.D0
  else
  b=bold
  endif
if (dabs(cold-1.D0).lt.0.001) then
  c=1.D0
  else
  c=cold
  endif
do i=1,6
  do j=1,6
    s(i,j)=0.0
    s1(i,j)=0.0
    enddo
  enddo
  ip=0
  ia=0.0
  ib=0.0
  ic=0.0
  iab=0.0
  ibc=0.0
  iac=0.0
  iaa=0.0
  ibb=0.0
  icc=0.0
if ((a.eq.b).and.(b.eq.c)) then
  s1111=(8.D0*mu1+9.D0*k1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s2222=(8.D0*mu1+9.D0*k1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s3333=(8.D0*mu1+9.D0*k1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s1122=(3.D0*k1-4.D0*mu1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s1133=(3.D0*k1-4.D0*mu1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s2233=(3.D0*k1-4.D0*mu1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s2211=(3.D0*k1-4.D0*mu1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s3311=(3.D0*k1-4.D0*mu1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s3322=(3.D0*k1-4.D0*mu1)/(5.D0*(4.D0*mu1+3.D0*k1))
  s1212=(3.D0*(2.D0*mu1+k1))/(5.D0*(4.D0*mu1+3.D0*k1))
  s1313=(3.D0*(2.D0*mu1+k1))/(5.D0*(4.D0*mu1+3.D0*k1))
  s2323=(3.D0*(2.D0*mu1+k1))/(5.D0*(4.D0*mu1+3.D0*k1))
go to 99
endif
if (((a.gt.c).and.(c.gt.b)).or.((a.eq.c).and.(c.gt.b))) then
c   interchange 2 and 3
  a1=a
  b1=b
  c1=c
  b=c
  c=b1
  ip=1
endif
if (((b.gt.a).and.(a.gt.c)).or.((a.eq.c).and.(c.lt.b))) then
c   interchange 1 and 2
  a1=a
  b1=b
  c1=c
  a=b
  b=a1
  ip=2
endif
if (((b.gt.c).and.(c.gt.a)).or.((b.eq.c).and.(b.gt.a))) then
c   make 2->1, 3->2, 1->3
  a1=a
  b1=b
  c1=c
  a=b
  b=c
  c=a1
  ip=3
endif
if ((c.gt.b).and.(b.gt.a)) then
c   interchange 1 and 3
  a1=a
  b1=b
  c1=c
  a=c
  c=a1
  ip=4
endif
if (((c.gt.a).and.(a.gt.b)).or.((a.eq.b).and.(b.lt.c))) then
c   make 3->1, 1->2, 2->3
  a1=a
  b1=b
  c1=c
  a=c

```

```

b=a1
c=b1
ip=5
endif
if ((a.eq.b).and.(b.gt.c)) then
call flush(15)
ia=2.D0*p*a*a*c/(a*a-c*c)
ia=ia/dsqrt(a*a-c*c)
ia=ia*(dacos(c/a)-((c/a)*dsqrt(1.D0-((c/a)**2))))
ib=ia
ic=4.D0*p-ia-ib
ibc=(ic-ib)/(3.D0*(b*b-c*c))
iac=(ic-ia)/(3.D0*(a*a-c*c))
iab=0.25*((4.D0*p)/(3.D0*a*a))-iac
iba=iab
ica=iac
icb=ibc
iaa=3.D0*iab
ibb=((4.D0*p)/(3.D0*b*b))-iba-ibc
icc=((4.D0*p)/(3.D0*c*c))-ica-icb
go to 98
endif
if ((b.eq.c).and.(a.gt.b)) then
call flush(15)
ib=2.D0*p*a*c*c/(a*a-c*c)
ib=ib/dsqrt(a*a-c*c)
ib=ib*((a/c)*dsqrt(((a/c)**2)-1.D0))-
& dlog((a/c)+dsqrt((a/c)**2-1.D0)))
ic=ib
ia=4.D0*p-ib-ic
iab=(ib-ia)/(3.D0*(a*a-b*b))
iac=(ic-ia)/(3.D0*(a*a-c*c))
ibc=0.25*((4.D0*p)/(3.D0*b*b))-iab
iba=iab
ica=iac
icb=ibc
iaa=((4.D0*p)/(3.D0*a*a))-iab-iac
icc=((4.D0*p)/(3.D0*c*c))-ica-icb
ibb=3.D0*ibc
go to 98
endif
c----- input value of a,b and c
if ((a.gt.b).and.(b.gt.c)) then
ia=4.D0*p*a*b*c/(a*a-b*b)
ia=ia/dsqrt((a*a-c*c))
x=dsqrt(((a/c)**2)-1.D0)
qqc=b*b-c*c
qqc=qqc/(a*a-c*c)
qqc=dsqrt(qqc)
aa=1.D0
bb=1.D0
ff=e12(x,qqc,aa,bb)
qqc2=qqc**2
aa=1.D0
bb=1.D0
e=e12(x,qqc,aa,qqc2)
ia=ia*(ff-e)
ic=4.D0*p*a*b*c/(b*b-c*c)
ic=ic/(dsqrt(a*a-c*c))
ic=ic*((b*(dsqrt(a*a-c*c))/(a*c))-e)
ib=4.D0*p-ia-ic
iab=(ib-ia)/(3.D0*(a*a-b*b))
ibc=(ic-ib)/(3.D0*(b*b-c*c))
iac=(ic-ia)/(3.D0*(a*a-c*c))
iba=iab
ica=iac
icb=ibc
iaa=((4.D0*p)/(3.D0*a*a))-iab-iac
ibb=((4.D0*p)/(3.D0*b*b))-iba-ibc
icc=((4.D0*p)/(3.D0*c*c))-ica-icb
endif
c----- elements of S
98   q=3.D0/(8.D0*p)
q=q/(1.D0-nu)
r=1.D0-2.D0*nu
r=r/(8.D0*p*(1.D0-nu))
s1111=q*a*a*iaa+r*ia
s2222=q*b*b*ibb+r*ib
s3333=q*c*c*icc+r*ic
s1122=q*b*b*iab-r*ia
s1133=q*c*c*iac-r*ia
s2233=q*c*c*icb-r*ib
s2211=q*a*a*iba-r*ib
s3311=q*a*a*ica-r*ic

```

```

s3322=q*b*b*icb-r*ic
s1212=0.5*q*(a*a+b*b)*iab+0.5*r*(ia+ib)
s1313=0.5*q*(a*a+c*c)*iac+0.5*r*(ia+ic)
s2323=0.5*q*(b*b+c*c)*ibc+0.5*r*(ib+ic)
99 continue
if (spath.eq..true.) then
  s(1,1)=s1111
  s(1,2)=s1122
  s(1,3)=s1133
  s(2,1)=s2211
  s(2,2)=s2222
  s(2,3)=s2233
  s(3,1)=s3311
  s(3,2)=s3322
  s(3,3)=s3333
  s(4,4)=2.D0*s1212
  s(5,5)=2.D0*s2323
  s(6,6)=2.D0*s1313
do 100 i=1,6
  do 110 j=1,6
    s1(i,j)=s(i,j)
  continue
100 continue
110 if (ip.eq.1) then
  s(1,2)=s1(1,3)
  s(1,3)=s1(1,2)
  s(2,1)=s1(3,1)
  s(2,2)=s1(3,3)
  s(2,3)=s1(3,2)
  s(3,1)=s1(2,1)
  s(3,2)=s1(2,3)
  s(3,3)=s1(2,2)
  s(4,4)=s1(6,6)
  s(6,6)=s1(4,4)
else if (ip.eq.2) then
  s(1,1)=s1(2,2)
  s(1,2)=s1(2,1)
  s(1,3)=s1(2,3)
  s(2,1)=s1(1,2)
  s(2,2)=s1(1,1)
  s(2,3)=s1(1,3)
  s(3,1)=s1(3,2)
  s(3,2)=s1(3,1)
  s(5,5)=s1(6,6)
  s(6,6)=s1(5,5)
else if (ip.eq.3) then
  s(1,1)=s1(3,3)
  s(1,2)=s1(3,1)
  s(1,3)=s1(3,2)
  s(2,1)=s1(1,3)
  s(2,2)=s1(1,1)
  s(2,3)=s1(1,2)
  s(3,1)=s1(2,3)
  s(3,2)=s1(2,1)
  s(3,3)=s1(2,2)
  s(4,4)=s1(6,6)
  s(5,5)=s1(4,4)
  s(6,6)=s1(5,5)
else if (ip.eq.4) then
  s(1,1)=s1(3,3)
  s(1,2)=s1(3,2)
  s(1,3)=s1(3,1)
  s(2,1)=s1(2,3)
  s(2,3)=s1(2,1)
  s(3,1)=s1(1,3)
  s(3,2)=s1(1,2)
  s(3,3)=s1(1,1)
  s(4,4)=s1(5,5)
  s(5,5)=s1(4,4)
else if (ip.eq.5) then
  s(1,1)=s1(2,2)
  s(1,2)=s1(2,3)
  s(1,3)=s1(2,1)
  s(2,1)=s1(3,2)
  s(2,2)=s1(3,3)
  s(2,3)=s1(3,1)
  s(3,1)=s1(1,2)
  s(3,2)=s1(1,3)
  s(3,3)=s1(1,1)
  s(4,4)=s1(5,5)
  s(5,5)=s1(6,6)
  s(6,6)=s1(4,4)
endif
else

```

```

c----- elements of Pi
q=3.D0/(8.D0*p)
q=q/(1.D0-nu)
r=1.D0-2.D0*nu
r=r/(8.D0*p*(1.D0-nu))
P1313=(ic-ia)/(8.D0*p)
P1331=(ic-ia)/(8.D0*p)
P3131=(ia-ic)/(8.D0*p)
P3113=(ia-ic)/(8.D0*p)
P1212=(ib-ia)/(8.D0*p)
P1221=(ib-ia)/(8.D0*p)
P2121=(ia(ib)/(8.D0*p)
P2112=(ia(ib)/(8.D0*p)
P3232=(ib-ic)/(8.D0*p)
P3223=(ib-ic)/(8.D0*p)
P2323=(ic-ib)/(8.D0*p)
P2332=(ic-ib)/(8.D0*p)
pp1212=p1212
pp1313=p1313
pp2323=p2323
pp1221=-pp1212
pp2121=pp1221
pp2112=-pp2121
pp1331=-pp1313
pp3131=pp1331
pp3113=-pp3131
pp2332=-pp2323
pp3232=pp2332
pp3223=-pp3232
if (ip.eq.1) then
  p1212=pp1313
  p1313=pp1212
  p2323=pp3232
else if (ip.eq.2) then
  p1212=pp2121
  p1313=pp2323
  p2323=pp1313
else if (ip.eq.3) then
  p1212=pp3131
  p1313=pp3232
  p2323=pp1212
else if (ip.eq.4) then
  p1212=pp3232
  p1313=pp3131
  p2323=pp2121
else if (ip.eq.5) then
  p1212=pp2323
  p1313=pp2121
  p2323=pp3131
endif
endif
if((ip.eq.1).or.(ip.eq.2).or.(ip.eq.3).or.(ip.eq.4).or.(ip.eq.5))
& then
  a=a1
  b=b1
  c=c1
endif
return
end

double precision FUNCTION EL2(X,QQC,AA,BB)
c implicit real*8 (a-h,o-z)
real*8 PI,ca,cb,x,qqc,aa,bb,qc,a,b,c,d,p
real*8 z,eye,y,ff,em,e,g
integer 1
PARAMETER(PI=3.14159265358979, CA=1.0D-6, CB=1.0D-12)
c PARAMETER(PI=3.14159265, CA=1.0D-6, CB=1.0D-12)
IF (X.EQ.0.0)THEN
  EL2=0.
ELSE IF(QQC.NE.0.0)THEN
  QC=QQC
  A=AA
  B=BB
  C=X**2
  D=1.D0+C
  P=DSQRT((1.D0+QC**2*C)/D)
  D=X/D
  C=D/(2.*P)
  Z=A-B
  EYE=A
  A=0.5*(B+A)
  Y=DABS(1.D0/X)
  FF=0.
  L=0
END IF
END FUNCTION EL2

```

```

EM=1.D0
QC=DABS(QC)
1 B=EYE*QC+B
E=EM*QC
G=E/P
D=FF*G+D
FF=C
EYE=A
P=G+P
C=0.5*(D/P+C)
G=EM
EM=QC+EM
A=0.5*(B/EM+A)
Y=-E/Y+Y
IF(Y.EQ.0.)Y=DSQRT(E)*CB
IF(DABS(G-QC).GT.CA*G)THEN
  QC=DSQRT(E)*2.
  L=L+L
  IF(Y.LT.0.)L=L+1
  GO TO 1
ENDIF
IF(Y.LT.0.)L=L+1
E=(DATAN(EM/Y)+PI*L)*A/EM
IF(X.LT.0.)E=-E
EL2=E+C*Z
ELSE
  PAUSE 'failure in EL2'
ENDIF
RETURN
END

```

```

C This is a routine to invert matrices (6x6)
subroutine inverse(a,y)
real*8 a(6,6),y(6,6),d
integer indx(6),i,j
do 10 i=1,6
  do 11 j=1,6
    if (i.eq.j) then
      y(i,j)=1.0
    else
      y(i,j)=0.0
    endif
11  continue
10  continue
call ludcmp(a,6,6,indx,d)
do 13 j=1,6
  call lubksb(a,6,6,indx,y(1,j))
13  continue
return
end
C=====

```

```

C This is a routine to invert matrices (3x3)
subroutine inverse3x3(a,y)
real*8 a(3,3),y(3,3),d
integer indx(3),i,j
do 10 i=1,3
  do 11 j=1,3
    if (i.eq.j) then
      y(i,j)=1.0
    else
      y(i,j)=0.0
    endif
11  continue
10  continue
call ludcmp(a,3,3,indx,d)
do 13 j=1,3
  call lubksb(a,3,3,indx,y(1,j))
13  continue
return
end
C=====

```

```

SUBROUTINE LUBKSB(A,N,NP,INDX,B)
implicit real*8 (a-h, o-z)
implicit integer (i-n)
real*8 A(NP,NP),B(N)
integer indx(n)
II=0
DO 12 I=1,N

```

```

LL=INDX(I)
SUM=B(LL)
B(LL)=B(I)
IF (II.NE.0) THEN
  DO 11 J=II,I-1
    SUM=SUM-A(I,J)*B(J)
11  CONTINUE
ELSE IF (SUM.NE.0.) THEN
  II=I
ENDIF
B(I)=SUM
12  CONTINUE
DO 14 I=N,1,-1
  SUM=B(I)
  IF (I.LT.N) THEN
    DO 13 J=I+1,N
      SUM=SUM-A(I,J)*B(J)
13  CONTINUE
  ENDIF
  B(I)=SUM/A(I,I)
14  CONTINUE
RETURN
END

```

```

SUBROUTINE LUDCMP(A,N,NP,INDX,D)
integer indx(n),nmax,np,n,i,j,k,imax
real*8 tiny,d
PARAMETER (NMAX=100,TINY=1.0E-20)
real*8 A(NP,NP),VV(NMAX),aamax,sum,dum
D=1.
DO 12 I=1,N
  AAMAX=0.
  DO 11 J=1,N
    IF (DABS(A(I,J)).GT.AAMAX) AAMAX=DABS(A(I,J))
11  CONTINUE
    IF (AAMAX.EQ.0.) PAUSE 'Singular matrix.'
    VV(I)=1./AAMAX
12  CONTINUE
DO 19 J=1,N
  IF (J.GT.1) THEN
    DO 14 I=1,J-1
      SUM=A(I,J)
      IF (I.GT.1)THEN
        DO 13 K=1,I-1
          SUM=SUM-A(I,K)*A(K,J)
13  CONTINUE
        A(I,J)=SUM
      ENDIF
14  CONTINUE
  ENDIF
  AAMAX=0.
  DO 16 I=J,N
    SUM=A(I,J)
    IF (J.GT.1)THEN
      DO 15 K=1,J-1
        SUM=SUM-A(I,K)*A(K,J)
15  CONTINUE
      A(I,J)=SUM
    ENDIF
    DUM=VV(I)*DABS(SUM)
    IF (DUM.GE.AAMAX) THEN
      IMAX=I
      AAMAX=DUM
    ENDIF
16  CONTINUE
  IF (J.NE.IMAX)THEN
    DO 17 K=1,N
      DUM=A(IMAX,K)
      A(IMAX,K)=A(J,K)
      A(J,K)=DUM
17  CONTINUE
    D=-D
    VV(IMAX)=VV(J)
  ENDIF
  INDX(J)=IMAX
  IF (J.NE.N)THEN
    IF (A(J,J).EQ.0.) A(J,J)=TINY
    DUM=1./A(J,J)
    DO 18 I=J+1,N
      A(I,J)=A(I,J)*DUM
18  CONTINUE
  ENDIF
19  CONTINUE

```

```

IF (A(N,N) .EQ. 0.) A(N,N)=TINY
RETURN
END

C This is a routine to multiply 6x6 matrices (remember 4th order tensors
C maybe written as 6x6 matrices without losing the tenosrial properties).
C subroutine tenprod(a,b,c)
real*8 a(6,6), b(6,6), c(6,6)
integer i,j,k
do 20 i=1,6
  do 30 j=1,6
    c(i,j)=0.0
30  continue
20  continue
do 10 i=1,6
  do 11 j=1,6
    do 12 k=1,6
      c(i,j)=a(i,k)*b(k,j)+c(i,j)
12  continue
11  continue
10  continue
return
end

C=====
subroutine tenmatprod(m,s,d)
real*8 m(6,6),s(6),d(6)
integer i,j
do 5 i=1,6
  d(i)=0.0
5  continue
do 10 i=1,6
  do 20 j=1,6
    d(i)=m(i,j)*s(j)+d(i)
20  continue
10  continue
return
end

C=====
subroutine rowcolumnprod(p,q,r)
real*8 p(6),q(6),r
integer i
r=0.0
do 5 i=1,6
  r=r+p(i)*q(i)
5  continue
return
end

C-----
C----- This is to calculate a part of the 'B' tensors for the composite
C----- subroutine Btensor(a,b,c,ad,bd,cd,c2,mu1,k1,mu2,k2,Bmat)
real*8 Bmat(6,6),L1(6,6),L2(6,6),Si(6,6)
real*8 M1(6,6),mu1,mu2,k1,k2,nu1,nu2
real*8 a,b,c,ad,bd,cd,c1,c2
real*8 d(6,6),d1(6,6)
real*8 pi1212,pi2323,pi1313
integer i,j
logical spath,debug
common /paths/spath
common /mdebug/debug
nu1=0.5*(3.0*k1-2.0*mu1)/(3.0*k1+mu1)
nu2=0.5*(3.0*k2-2.0*mu2)/(3.0*k2+mu2)
c1=1.0-c2
c Initialize the modulus tensors
do 10 i=1,6
  do 20 j=1,6
    L1(i,j)=0.0
    L2(i,j)=0.0
20  continue
10  continue
c Obtain the (6x6) modulus tensors, L1 and L2
L1(1,1)=k1+(4.0/3.0)*mu1
L1(2,2)=k1+(4.0/3.0)*mu1
L1(3,3)=k1+(4.0/3.0)*mu1
L1(1,2)=k1-(2.0/3.0)*mu1
L1(2,1)=k1-(2.0/3.0)*mu1
L1(2,3)=k1-(2.0/3.0)*mu1
L1(3,2)=k1-(2.0/3.0)*mu1

```

```

L1(3,1)=k1-(2.0/3.0)*mul
L1(1,3)=k1-(2.0/3.0)*mul
L1(4,4)=2.0*mul
L1(5,5)=2.0*mul
L1(6,6)=2.0*mul
L2(1,1)=k2+(4.0/3.0)*mu2
L2(2,2)=k2+(4.0/3.0)*mu2
L2(3,3)=k2+(4.0/3.0)*mu2
L2(1,2)=k2-(2.0/3.0)*mu2
L2(2,1)=k2-(2.0/3.0)*mu2
L2(2,3)=k2-(2.0/3.0)*mu2
L2(3,2)=k2-(2.0/3.0)*mu2
L2(3,1)=k2-(2.0/3.0)*mu2
L2(1,3)=k2-(2.0/3.0)*mu2
L2(4,4)=2.0*mu2
L2(5,5)=2.0*mu2
L2(6,6)=2.0*mu2
c Begin calculating B tensor
call inverse(L1,M1)
call tenprod(M1,L2,d)
do 30 i=1,6
  d(i,i)=d(i,i)-1.0
30 continue
call inverse(d,d1)
do 31 i=1,6
  do 32 j=1,6
    d(i,j)=0.0
32 continue
31 continue
c calculate S tensors
spath=.true.
call stensor(a,b,c,nul,k1,mul,si,pi1212,pi1313,pi2323)
do 60 i=1,6
  do 70 j=1,6
    d(i,j)=si(i,j)-c2*si(i,j)
70 continue
60 continue
do 80 i=1,6
  do 90 j=1,6
    d(i,j)=d(i,j)+d1(i,j)
90 continue
80 continue
call inverse(d,Bmat)
return
end

```

```

doubleprecision FUNCTION RTSAFE(FUNCD,X1,X2,XACC)
integer maxit,j
real*8 x1,x2,xacc,f1,df,fh,xl,xh,swap,dxold,dx,f,temp
logical neg,yield,check,cal
common /mkdata2/yield,check,neg
common /call/cal
external funcd
PARAMETER (MAXIT=100)
CALL FUNCD(X1,FL,DF)
if (neg.eq..true..) then
  write(15,'*)'RTSAFE1'
  call flush(15)
  return
endif
CALL FUNCD(X2,FH,DF)
if (neg.eq..true..) then
  write(15,'*)'RTSAFE2'
  call flush(15)
  return
endif
IF(FL*FH.GE.0.) THEN
  write(15,'*)'data', xl,x2,f1,fh
  call flush(15)
  PAUSE 'root must be bracketed'
ENDIF
IF(FL.LT.0.)THEN
  XL=X1
  XH=X2
ELSE
  XH=X1
  XL=X2
  SWAP=FL
  FL=FH
  FH=SWAP
ENDIF
RTSAFE=.5*(X1+X2)
DXOLD=DABS(X2-X1)

```

```

DX=DXOLD
CALL FUNCD(RTSAFE,F,DF)
if (neg.eq..true.) then
  write(15,*)'RTSAFE2'
  call flush(15)
  return
endif
DO 11 J=1,MAXIT
  IF(((RTSAFE-XH)*DF-F)*((RTSAFE-XL)*DF-F) .GE. 0.
*     .OR. DABS(2.D0*F).GT.ABS(DXOLD*DF) ) THEN
    DXOLD=DX
    DX=0.5*(XH-XL)
    RTSAFE=XL+DX
    IF(XL.EQ.RTSAFE) then
      if (cal.eq..true.) then
        write(15,*)'ITER',J
      endif
      RETURN
    endif
  ELSE
    DXOLD=DX
    DX=F/DF
    TEMP=RTSAFE
    RTSAFE=RTSAFE-DX
    IF(TEMP.EQ.RTSAFE) then
      if (cal.eq..true.) then
        write(15,*)'ITER',J
      endif
      RETURN
    endif
  ENDIF
  IF(DABS(DX).LT.XACC) then
    if (cal.eq..true.) then
      write(15,*)'ITER',J
    call flush(15)
  endif
  RETURN
  endif
  CALL FUNCD(RTSAFE,F,DF)
  if (neg.eq..true.) then
    return
  endif
  IF(F.LT.0.) THEN
    XL=RTSAFE
    FL=F
  ELSE
    XH=RTSAFE
    FH=F
  ENDIF
11 CONTINUE
c PAUSE 'RTSAFE exceeding maximum iterations'
write(15,*)'RTSAFE NOT GOOD'
call flush(15)
neg=.true.
RETURN
END

```

C=====

```

doubleprecision function func(dlam)
real*8 s(3,3),phi,MHS(6,6),Amat(6,6),Ce(6,6)
real*8 sn(3,3),n(3,3),omega(3,3),sige(3,3)
real*8 strainc(6),sigec(6),vec(3),R(3,3)
real*8 f,wi1,wi2,sci(6),dumd(6,6),RT(3,3)
real*8 fn,wi1n,wi2n,dlam,sigyln,dinc(6)
real*8 sc(6),nc(6),omegac(6),sig_n(6)
real*8 mu1,k1,mu2,k2,sigy1,sigma_n(6)
real*8 dummy(6),a,b,c,ad,bd,cd,dummy1(3,3),dummy2(3,3)
real*8 dummy5(6),dum1,dum2,sn1(3,3),sigy0
real*8 dep_plas,eps_plastic,deps(3,3),k11,eps_plasticn
real*8 an,bn,cn,adn,bdn,cdn,e1212,e2323,e1313
real*8 pi1212,pi2323,pi1313,bmat(6,6),nul
real*8 mule,kle,mu2e,ek2e,y,MHSn(6,6),dum5,dum10
real*8 cp,sp,ct,st,cs,ss,rot(3,3),rott(3,3),hrd
real*8 athetan,apsin,aphin,atheta,aphi,apsi
real*8 cpn,spn,ctn,stn,csn,ssn,rotn(3,3),rotnt(3,3)
real*8 loadp(6),loading
real*8 zero(6),totstrain(6)
real*8 rotj(3,3),rotjn(3,3),rota(3,3)
integer i,j,ninc

```

```

logical path,yield,check,neg,spath,yc,debug
logical evolf,evolwi,evolti
common /controls/evolf,evolwi,evolti
common /mkmodulus/mu1,k1,mu2,k2,sigy0,k11
common /mkdata1/f,wi1,wi2,sc,strainc,eps_plastic,sigy1,hrd
common /mkdata2/yield,check,neg
common /mkelas/mule,k1e,mu2e,ek2e
common /mkorient/cp,sp,ct,st,cs,ss,rot,rott,atheta,aphi,apsi
common /mkrot/R,RT,rotj
common /paths/spath
common /mdebug/debug

c
path=.true.
yield=.true.
neg=.false.
mu1=0.5*(3.0*k1-2.0*mu1)/(3.0*k1+mu1)
if(debug.eq..true.) then
write(15,*)'func1'
call flush(15)
endif
c
c=1.000
a=c/wi1
b=c/wi2
ad=a
bd=b
cd=c
c
c----- calculate Meffective
call Meffective(a,b,c,ad,bd,cd,f,mu1,k11,mu2,k2,MHS,path)
do 100 i=1,6
  do 110 j=1,6
    MHS(i,j)=3.0*mu1*MHS(i,j)
110  continue
100  continue
c
c----- Estimate stress
c----- STEP 1: Estimate the elastic predictor
path=.false.
call Meffective(a,b,c,ad,bd,cd,f,mule,k1e,mu2e,ek2e,Ce,path)
path=.true.
call tenmatprod(Ce,strainc,sigec)
do 201 i=1,6
  loadp(i)=sigec(i)
201  continue
  sige(1,1)=sc(1)+sigec(1)
  sige(2,2)=sc(2)+sigec(2)
  sige(3,3)=sc(3)+sigec(3)
  sige(1,2)=(sc(4)+sigec(4))/dsqrt(2.D0)
  sige(2,3)=(sc(5)+sigec(5))/dsqrt(2.D0)
  sige(3,1)=(sc(6)+sigec(6))/dsqrt(2.D0)
  sige(2,1)=sige(1,2)
  sige(3,2)=sige(2,3)
  sige(1,3)=sige(3,1)
  sigec(1)=sige(1,1)
  sigec(2)=sige(2,2)
  sigec(3)=sige(3,3)
  sigec(4)=sige(1,2)*dsqrt(2.D0)
  sigec(5)=sige(2,3)*dsqrt(2.D0)
  sigec(6)=sige(3,1)*dsqrt(2.D0)
c----- STEP 1a: Determining the stress on the yield surface
sigma_n(1)=sc(1)
sigma_n(2)=sc(2)
sigma_n(3)=sc(3)
sigma_n(4)=sc(4)
sigma_n(5)=sc(5)
sigma_n(6)=sc(6)
call yieldtest(MHS,sigma_n,sigy1,f,yc,y)
if (yc.eq..false.) then
  call yieldtest(MHS,sigec,sigy1,f,yc,y)
  if (yc.eq..true.) then
    this is the step where the behavior becomes plastic (the previous
    step was elastic)
    write(15,*)'Becoming plastic'
    do 127 i=1,6
      zero(i)=0.0
      totstrain(i)=strainc(i)
      continue
      ninc=100.0
      call stre(sigma_n,sigec,zero,totstrain,sig_n,Ce,ninc)
    else
      write(15,*)'NOT PLASTIC'
      call flush(15)
127

```

```

      do 130 i=1,6
        sig_n(i)=sc(i)
      continue
    endif
  else
    call flush(15)
    do 131 i=1,6
      sig_n(i)=sc(i)
    continue
  endif
c----- calculate N(3,3)
call tenmatprod(MHS,sig_n,nc)
do 200 i=1,6
  nc(i)=nc(i)/(1.0-f)
  nc(i)=2.0*nc(i)/sigy1
  dummy(i)=nc(i)
  dummy5(i)=nc(i)
200 continue
n(1,1)=nc(1)
n(2,2)=nc(2)
n(3,3)=nc(3)
n(1,2)=nc(4)/dsqrt(2.D0)
n(2,1)=n(1,2)
n(2,3)=nc(5)/dsqrt(2.D0)
n(3,2)=n(2,3)
n(3,1)=nc(6)/dsqrt(2.D0)
n(1,3)=n(3,1)
call rowcolumnprod(loadp,dummy5,loading)
if (loading.le.0.0) then
  write(15,'(*)'loading in func',loading
endif
do 202 i=1,6
  dummy5(i)=nc(i)
202 continue
c----- STEP 2: Remaining part of the stress
c----- STEP 2a: Calculating 'omega'
  spath=.false.
do 17 i=1,6
  do 18 j=1,6
    dumd(i,j)=0.0
18   continue
17   continue
if(debug.eq..true.) then
  write(15,'(*)'func3',a,b,c,nu1,k1,mu1,dumd,pi1212,pi1313,
&                           pi2323
  call flush(15)
endif
  call stensor(a,b,c,nu1,k1,mu1,dumd,pi1212,pi1313,pi2323)
  e1212=pi1212-f*pi1212
  e2323=pi2323-f*pi2323
  e1313=pi1313-f*pi1313
  spath=.true.
if(debug.eq..true.) then
  write(15,'(*)'func3_a',ad,bd,cd,a,b,c
  call flush(15)
endif
  call Btensor(a,b,c,ad,bd,cd,f,mu1,k1,mu2,k2,Bmat)
do 41 i=1,3
  do 42 j=1,6
    Bmat(i,j)=0.0
42   continue
41   continue
Bmat(4,1)=-2.0*e1212*Bmat(4,1)
Bmat(4,2)=-2.0*e1212*Bmat(4,2)
Bmat(4,3)=-2.0*e1212*Bmat(4,3)
Bmat(4,4)=-2.0*e1212*Bmat(4,4)
Bmat(4,5)=-2.0*e1212*Bmat(4,5)
Bmat(4,6)=-2.0*e1212*Bmat(4,6)
Bmat(5,1)=-2.0*e2323*Bmat(5,1)
Bmat(5,2)=-2.0*e2323*Bmat(5,2)
Bmat(5,3)=-2.0*e2323*Bmat(5,3)
Bmat(5,4)=-2.0*e2323*Bmat(5,4)
Bmat(5,5)=-2.0*e2323*Bmat(5,5)
Bmat(5,6)=-2.0*e2323*Bmat(5,6)
Bmat(6,1)=-2.0*e1313*Bmat(6,1)
Bmat(6,2)=-2.0*e1313*Bmat(6,2)
Bmat(6,3)=-2.0*e1313*Bmat(6,3)
Bmat(6,4)=-2.0*e1313*Bmat(6,4)
Bmat(6,5)=-2.0*e1313*Bmat(6,5)
Bmat(6,6)=-2.0*e1313*Bmat(6,6)
if(debug.eq..true.) then
  write(15,'(*)'func3_b',a,b,c,ad,bd,cd
  call flush(15)
endif

```

```

call Atensor(a,b,c,ad,bd,cd,f,mul,k1,mu2,k2,Amat)
c-----
if(debug.eq..true.) then
write(15,*)'func4'
call flush(15)
endif
do 3 i=1,3
  do 4 j=1,3
    omega(i,j)=0.0
  continue
3 continue
do 1 i=1,3
  omega(1,2)=-Bmat(4,i)*nc(i)+omega(1,2)
  omega(2,3)=-Bmat(5,i)*nc(i)+omega(2,3)
  omega(1,3)=-Bmat(6,i)*nc(i)+omega(1,3)
1 continue
do 2 i=4,6
  omega(1,2)=-Bmat(4,i)*nc(i)+omega(1,2)
  omega(2,3)=-Bmat(5,i)*nc(i)+omega(2,3)
  omega(1,3)=-Bmat(6,i)*nc(i)+omega(1,3)
2 continue
omega(2,1)=-omega(1,2)
omega(3,2)=-omega(2,3)
omega(3,1)=-omega(1,3)
do 7 i=1,3
  do 8 j=1,3
    omega(i,j)=omega(i,j)/dsqrt(2.0d0)
  continue
8 continue
continue
call tenmatprod(Amat,nc,dinc)
  if (dabs(a-b).gt.0.01) then
    omega(1,2)=omega(1,2)-(a*a+b*b)*dinc(4)/(dsqrt(2.0d0)*(a*a-b*b))
  endif
  if (dabs(a-c).gt.0.01) then
    omega(1,3)=omega(1,3)-(a*a+c*c)*dinc(6)/(dsqrt(2.0d0)*(a*a-c*c))
  endif
  if (dabs(c-b).gt.0.01) then
    omega(2,3)=omega(2,3)-(b*b+c*c)*dinc(5)/(dsqrt(2.0d0)*(b*b-c*c))
  endif
omega(2,1)=-omega(1,2)
omega(3,2)=-omega(2,3)
omega(3,1)=-omega(1,3)
omegac(1)=omega(1,1)
omegac(2)=omega(2,2)
omegac(3)=omega(3,3)
omegac(4)=omega(1,2)*dsqrt(2.D0)
omegac(5)=omega(2,3)*dsqrt(2.D0)
omegac(6)=omega(1,3)*dsqrt(2.D0)
c-----
s(1,1)=sc(1)
s(2,2)=sc(2)
s(3,3)=sc(3)
s(1,2)=sc(4)/dsqrt(2.D0)
s(2,3)=sc(5)/dsqrt(2.D0)
s(3,1)=sc(6)/dsqrt(2.D0)
s(2,1)=s(1,2)
s(3,2)=s(2,3)
s(1,3)=s(3,1)
c   write(15,*)'In func',sc
c   call flush(15)
call matprod(s,omega,dummy1)
call matprod(omega,s,dummy2)
do 300 i=1,3
  do 310 j=1,3
    sn(i,j)=dummy1(i,j)-dummy2(i,j)
ccc   sn(i,j)=0.0
310   continue
300   continue
do 450 i=1,6
  dummy5(i)=nc(i)
450   continue
if(debug.eq..true.) then
write(15,*)'func5'
call flush(15)
endif
call tenmatprod(Ce,dummy5,dummy)
  sn(1,1)=sn(1,1)-dummy(1)
  sn(2,2)=sn(2,2)-dummy(2)
  sn(3,3)=sn(3,3)-dummy(3)
  sn(1,2)=sn(1,2)-dummy(4)/dsqrt(2.D0)
  sn(2,3)=sn(2,3)-dummy(5)/dsqrt(2.D0)
  sn(3,1)=sn(3,1)-dummy(6)/dsqrt(2.D0)
  sn(2,1)=sn(1,2)
  sn(3,2)=sn(2,3)

```

```

sn(1,3)=sn(3,1)
do 320 i=1,3
  do 330 j=1,3
    dummy1(i,j)=sn(i,j)
330   continue
320   continue
c----- STEP 3: put them together
sn1(1,1)=sige(1,1)+dlam*sn(1,1)
sn1(2,2)=sige(2,2)+dlam*sn(2,2)
sn1(3,3)=sige(3,3)+dlam*sn(3,3)
sn1(1,2)=sige(1,2)+dlam*sn(1,2)
sn1(2,3)=sige(2,3)+dlam*sn(2,3)
sn1(3,1)=sige(3,1)+dlam*sn(3,1)
sn1(2,1)=sn1(1,2)
sn1(3,2)=sn1(2,3)
sn1(1,3)=sn1(3,1)
c----- These components of sn1 are now NOT in the coordinate frame
c----- coincides with the orientation of the inclusions. This is due
c----- to the algorithm used (see notes for more details). In order to
c----- obtain them in this coordinate frame:
call matprod(R,sn1,dummy1)
call matprod(dummy1,RT,sn1)
c   write(15,*)'sn1',sn1(3,3)
ccall flush(15)
c----- estimate the new state variables for this iteration
if(debug.eq..true.) then
write(15,*)'func6'
call flush(15)
endif
call Atensor(a,b,c,ad,bd,cd,f,mu1,k1,mu2,k2,Amat)
if(debug.eq..true.) then
write(15,*)'func6a'
call flush(15)
endif
if (evolf.eq..true.) then
fn=f+(n(1,1)+n(2,2)+n(3,3))*(1.0-f)*dlam
else
fn=f
endif
if ((fn.lt.0.0).or.(fn.gt.1.0)) then
write(15,*)'porosity estimate wrong',f,dlam
call flush(15)
c   neg=.true.
c   return
f=0.0
endif
dummy(1)=Amat(3,1)-Amat(1,1)
dummy(2)=Amat(3,2)-Amat(1,2)
dummy(3)=Amat(3,3)-Amat(1,3)
dummy(4)=Amat(3,4)-Amat(1,4)
dummy(5)=Amat(3,5)-Amat(1,5)
dummy(6)=Amat(3,6)-Amat(1,6)
call rowcolumnprod(dummy,dummy5,dum1)
do 400 i=1,6
  dummy5(i)=nc(i)
400 continue
dummy(1)=Amat(3,1)-Amat(2,1)
dummy(2)=Amat(3,2)-Amat(2,2)
dummy(3)=Amat(3,3)-Amat(2,3)
dummy(4)=Amat(3,4)-Amat(2,4)
dummy(5)=Amat(3,5)-Amat(2,5)
dummy(6)=Amat(3,6)-Amat(2,6)
call rowcolumnprod(dummy,dummy5,dum2)
if(debug.eq..true.) then
write(15,*)'func6b'
call flush(15)
endif
if (evolwi.eq..true.) then
wi1n=wi1+dlam*wi1*dum1
wi2n=wi2+dlam*wi2*dum2
else
wi1n=wi1
wi2n=wi2
endif
dum5=dum1
dum10=dum2
if ((wi1n.le.0.0).or.(wi2n.le.0.0)) then
write(15,*)'aspect estimate wrong','dlam=',dlam
call flush(15)
neg=.true.
return
endif
c----- estimating new orientations

```

```

if (evolti.eq..true.) then
  athetan=atheta-(omega(2,3)*cp+omega(1,3)*sp)*dlam
if (dabs(wi2n-1.0).lt.0.01) then
  athetan=0.0
endif
if (st.ne.0.0) then
  aphin=aphi-((omega(2,3)*ss/st)-omega(1,3)*cs/st)*dlam
  apsin=apsi+(-omega(1,2)+(ct/st)*(omega(2,3)*ss-omega(1,3)*cs))*dlam
& else
  apsin=0.0
  aphin=0.0
endif
call matprod(R,rotj,rotjn)
else
  aphin=aphi
  apsin=apsi
  athetan=atheta
do 27 i=1,3
do 28 j=1,3
  rotjn(i,j)=rotj(i,j)
  continue
  continue
endif
ctn=dcos(athetan)
stn=dsin(athetan)
cpn=dcos(aphin)
csn=dcos(apsin)
spn=dsin(aphin)
ssn=dsin(apsin)
rota(1,1)=csn*cpn-ssn*ctn*spn
rota(1,2)=-csn*spn-ssn*ctn*cpn
rota(1,3)=ssn*stn
rota(2,1)=ssn*cpn+csn*ctn*spn
rota(2,2)=-ssn*spn+csn*ctn*cpn
rota(2,3)=-csn*stn
rota(3,1)=stn*spn
rota(3,2)=stn*cpn
rota(3,3)=ctn
call matprod(rota,rotjn,rotn)
do 77 i=1,3
do 88 j=1,3
  rotnt(i,j)=rotn(j,i)
  continue
  continue
c----- estimating new sig_yield
do 501 i=1,3
do 502 j=1,3
  deps(i,j)=dlam*n(i,j)
502 continue
501 continue
duml=(deps(1,1)+deps(2,2)+deps(3,3))/3.0
do 503 i=1,3
  deps(i,i)=deps(i,i)-duml
503 continue
dep_plas=deps(1,1)**2+deps(2,2)**2+deps(3,3)**2
dep_plas=dep_plas+2.0*(deps(1,2)**2+deps(2,3)**2+deps(3,1)**2)
dep_plas=(2.0/3.0)*dep_plas
ccc  eps_plasticcn=eps_plastic+dsqrt(dep_plas)
      sigyln=sigy0*((1.0+eps_plasticcn)**(1.0/3.0))
      sigyln=sigy1
c-----
c----- calculate the yield function with these new values of the stress
c and state variables.....
c
c
cn=1.000
an=cn/wi1n
bn=cn/wi2n
adn=an
bdn=bn
cdn=cn
call Meffective(an,bn,cn,adn,bdn,cdn,fn,mul,k11,mu2,k2,MHSn,path)
do 500 i=1,6
do 510 j=1,6
  MHSn(i,j)=3.0*mul*MHSn(i,j)
510 continue
500 continue
c----- The stress must now be expressed w.r.t the new basis -- the basis
c which is aligned with the current (new) orientation of the voids. This is
c the basis in which the components of MHSn are obtained.
c
c----- This expresses sn1 in GLOBAL frame.
  call matprod(rot,sn1,dummy)

```

```

    call matprod(dummy,rott,sn1)
c----- This expresses sn1 w.r.t new orientation of particles
    call matprod(rotnt,sn1,dummy)
    call matprod(dummy,rotnt,sn1)

c
    sci(1)=sn1(1,1)
    sci(2)=sn1(2,2)
    sci(3)=sn1(3,3)
    sci(4)=sn1(1,2)*dsqrt(2.D0)
    sci(5)=sn1(2,3)*dsqrt(2.D0)
    sci(6)=sn1(3,1)*dsqrt(2.D0)
    call tenmatprod(MHSn,sci,dummy)
    call rowcolumnprod(sci,dummy,phi)
    phi=phi/((1.0-fn)*sigy1n)
    phi=phi-sigy1n
    func=phi
    return
end

doubleprecision FUNCTION RTNEWT(FUNCD,X2,XACC)
integer jmax,j
c implicit doubleprecision(a-h,o-z)
real*8 x2,xacc,f,df,dx
logical neg,check,yield
common /mkdata2/yield,check,neg
external funcd
PARAMETER (JMAX=20)
rtnewt=x2
DO 11 J=1,JMAX
    CALL FUNCD(RTNEWT,F,DF)
if (neg.eq..true.) then
    return
endif
DX=F/DF
RTNEWT=RTNEWT-DX
c RTNEWT=RTNEWT-0.000001
IF(DABS(DX).LT.XACC) then
    RETURN
endif
11 CONTINUE
c PAUSE 'RTNEWT exceeding maximum iterations'
write(15,*)'RTNEWT NOT GOOD'
call flush(15)
neg=.true.
END

subroutine guessmaker(dlam)
real*8 MHS(6,6),Ce(6,6)
real*8 n(3,3),sige(3,3),L
real*8 strainc(6),sigec(6)
real*8 f,wil,wi2
real*8 cp,sp,ct,st,cs,ss,rot(3,3),rott(3,3),atheta,aphi,apsi
real*8 dlam,sigy0
real*8 sc(6),nc(6),sig_n(6)
real*8 mul,k1,mu2,k2,sigy1,sigma_n(6)
real*8 dummy(6),a,b,c,ad,bd,cd
real*8 dummy5(6),k11,mule,kle,mu2e,ek2e,eps_plastic
real*8 phil,ftest,phi2,dphidf,h,wiltest,ate,bte
real*8 dphidwil,wil2test,dphidwi2,dum5,dum10,y
real*8 omega(3,3),omegac(6),dummy1(3,3),dummy2(3,3)
real*8 bmat(6,6),amat(6,6),dumd(6,6),dinc(6),hrd
real*8 pi1212,pi2323,pi1313,e1212,e2323,e1313
real*8 nul,zero(6),totstrain(6)
integer i,j,ninc
logical path,yield,check,neg,yc,spath,debug
logical evolf,evolwi,evolti
common /controls/evolf,evolwi,evolti
common /mkmodulus/mul,k1,mu2,k2,sigy0,k11
common /mkelas/mule,kle,mu2e,ek2e
common /mkdata1/f,wil,wi2,sc,strainc,eps_plastic,sigy1,hrd
common /mkorient/cp,sp,ct,st,cs,ss,rot,rott,atheta,aphi,apsi
common /mkdata2/yield,check,neg
common /mdebug/debug

c
path=.true.
yield=.true.
c=1.000
a=c/wil
b=c/wi2
ad=a

```

```

bd=b
cd=c
c
c----- Estimate stress
c----- STEP 1: Estimate the elastic predictor
path=.false.
call Meffective(a,b,c,ad,bd,cd,f,mule,kle,mu2e,ek2e,Ce,path)
path=.true.
call tenmatprod(Ce,strainc,sigec)
sige(1,1)=sc(1)+sigec(1)
sige(2,2)=sc(2)+sigec(2)
sige(3,3)=sc(3)+sigec(3)
sige(1,2)=(sc(4)+sigec(4))/dsqrt(2.D0)
sige(2,3)=(sc(5)+sigec(5))/dsqrt(2.D0)
sige(3,1)=(sc(6)+sigec(6))/dsqrt(2.D0)
sige(2,1)=sige(1,2)
sige(3,2)=sige(2,3)
sige(1,3)=sige(3,1)
sigec(1)=sige(1,1)
sigec(2)=sige(2,2)
sigec(3)=sige(3,3)
sigec(4)=sige(1,2)*dsqrt(2.D0)
sigec(5)=sige(2,3)*dsqrt(2.D0)
sigec(6)=sige(3,1)*dsqrt(2.D0)
c----- Test for yielding...
c----- calculate yield function with stress=elastic predictor
call Meffective(a,b,c,ad,bd,cd,f,mul,k1,mu2,k2,MHS,path)
do 101 i=1,6
  do 111 j=1,6
    MHS(i,j)=3.0*mul*MHS(i,j)
  continue
101 continue
call yieldtest(MHS,sigec,sigy1,f,yc,y)
if (yc.eq..false.) then
  yield=.false.
  go to 999
endif
if(debug.eq..true.) then
  write(15,'*')'guess2'
  call flush(15)
endif
c----- STEP 1a: Determining the stress on the yield surface
sigma_n(1)=sc(1)
sigma_n(2)=sc(2)
sigma_n(3)=sc(3)
sigma_n(4)=sc(4)
sigma_n(5)=sc(5)
sigma_n(6)=sc(6)
call yieldtest(MHS,sigma_n,sigy1,f,yc,y)
if (yc.eq..false.) then
  call yieldtest(MHS,sigec,sigy1,f,yc,y)
  if (yc.eq..true.) then
    this is the step where the behavior becomes plastic (the previous
    step was elastic)
  do 127 i=1,6
    zero(i)=0.0
    totstrain(i)=strainc(i)
127  continue
    ninc=100.0
    call stre(sigma_n,sigec,zero,totstrain,sig_n,Ce,ninc)
  else
    do 130 i=1,6
      sig_n(i)=sc(i)
130  continue
    endif
  else
    do 131 i=1,6
      sig_n(i)=sc(i)
131  continue
    endif
c----- calculate N(3,3)
call tenmatprod(MHS,sig_n,nc)
do 200 i=1,6
  nc(i)=nc(i)/(1.0-f)
  nc(i)=2.0*nc(i)/sigy1
200  continue
n(1,1)=nc(1)
n(2,2)=nc(2)
n(3,3)=nc(3)
n(1,2)=nc(4)/dsqrt(2.D0)
n(2,1)=n(1,2)
n(2,3)=nc(5)/dsqrt(2.D0)
n(3,2)=n(2,3)

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```

n(3,1)=nc(6)/dsqrt(2.D0)
n(1,3)=n(3,1)
c-----
c----- calculate guess
do 410 i=1,6
  dummy5(i)=nc(i)
410 continue
call tenmatprod(Ce,dummy5,dummy)
do 420 i=1,6
  dummy5(i)=nc(i)
420 continue
call rowcolumnprod(dummy,dummy5,L)
if(debug.eq..true.) then
write(15,'*')'guess3'
call flush(15)
endif
c----- calculating omega
spath=.false.
nul=0.5*(3.0*k1-2.0*mul)/(3.0*k1+mul)
call stensor(a,b,c,nul,k1,mul,dumd,pi1212,pi1313,pi2323)
e1212=pi1212-f*pi1212
e2323=pi2323-f*pi2323
e1313=pi1313-f*pi1313
spath=.true.
call Btensor(a,b,c,ad,bd,cd,f,mul,k1,mu2,k2,Bmat)
do 41 i=1,3
  do 42 j=1,6
    Bmat(i,j)=0.0
  continue
41 continue
Bmat(4,1)=2.0*e1212*Bmat(4,1)
Bmat(4,2)=2.0*e1212*Bmat(4,2)
Bmat(4,3)=2.0*e1212*Bmat(4,3)
Bmat(4,4)=2.0*e1212*Bmat(4,4)
Bmat(4,5)=2.0*e1212*Bmat(4,5)
Bmat(4,6)=2.0*e1212*Bmat(4,6)
Bmat(5,1)=2.0*e2323*Bmat(5,1)
Bmat(5,2)=2.0*e2323*Bmat(5,2)
Bmat(5,3)=2.0*e2323*Bmat(5,3)
Bmat(5,4)=2.0*e2323*Bmat(5,4)
Bmat(5,5)=2.0*e2323*Bmat(5,5)
Bmat(5,6)=2.0*e2323*Bmat(5,6)
Bmat(6,1)=2.0*e1313*Bmat(6,1)
Bmat(6,2)=2.0*e1313*Bmat(6,2)
Bmat(6,3)=2.0*e1313*Bmat(6,3)
Bmat(6,4)=2.0*e1313*Bmat(6,4)
Bmat(6,5)=2.0*e1313*Bmat(6,5)
Bmat(6,6)=2.0*e1313*Bmat(6,6)
call Atensor(a,b,c,ad,bd,cd,f,mul,k1,mu2,k2,Amat)
do 3 i=1,3
  do 4 j=1,3
    omega(i,j)=0.0
  continue
4 continue
3 continue
do 1 i=1,3
  omega(1,2)=-Bmat(4,i)*nc(i)+omega(1,2)
  omega(2,3)=-Bmat(5,i)*nc(i)+omega(2,3)
  omega(1,3)=-Bmat(6,i)*nc(i)+omega(1,3)
1 continue
do 2 i=4,6
  omega(1,2)=-Bmat(4,i)*nc(i)+omega(1,2)
  omega(2,3)=-Bmat(5,i)*nc(i)+omega(2,3)
  omega(1,3)=-Bmat(6,i)*nc(i)+omega(1,3)
2 continue
omega(2,1)=-omega(1,2)
omega(3,2)=-omega(2,3)
omega(3,1)=-omega(1,3)
do 7 i=1,3
  do 8 j=1,3
    omega(i,j)=omega(i,j)/dsqrt(2.0d0)
  continue
7 continue
call tenmatprod(Amat,nc,dinc)
  if (dabs(a-b).gt.0.01) then
  omega(1,2)=omega(1,2)-(a*a+b*b)*dinc(4)/(dsqrt(2.0d0)*(a*a-b*b))
  endif
  if (dabs(a-c).gt.0.01) then
  omega(1,3)=omega(1,3)-(a*a+c*c)*dinc(6)/(dsqrt(2.0d0)*(a*a-c*c))
  endif
  if (dabs(c-b).gt.0.01) then
  omega(2,3)=omega(2,3)-(b*b+c*c)*dinc(5)/(dsqrt(2.0d0)*(b*b-c*c))
  endif
  omega(2,1)=-omega(1,2)
  omega(3,2)=-omega(2,3)

```

```

omega(3,1)=-omega(1,3)
omegac(1)=omega(1,1)
omegac(2)=omega(2,2)
omegac(3)=omega(3,3)
omegac(4)=omega(1,2)*dsqrt(2.D0)
omegac(5)=omega(2,3)*dsqrt(2.D0)
omegac(6)=omega(1,3)*dsqrt(2.D0)
call matprod(sig_n,omega,dummy1)
call matprod(omega,sig_n,dummy2)
do 12 i=1,3
  do 13 j=1,3
    dummy1(i,j)=dummy1(i,j)-dummy2(i,j)
13  continue
12  continue
do 14, i=1,3
  do 15 j=1,3
    L=L-dummy1(i,j)*n(i,j)
15  continue
14  continue
c----- calculating H
if(debug.eq..true.) then
write(15,*)"guess4"
call flush(15)
endif
c----- step A -- calculating dphi/df
H=0.0
if (evolf.eq..true.) then
  path=.true.
  call Meffective(a,b,c,ad,bd,cd,f,mul,k11,mu2,k2,MHS,path)
  do 1001 i=1,6
    do 1002 j=1,6
      MHS(i,j)=3.0*mul*MHS(i,j)
1002  continue
1001  continue
  call yieldtest(MHS,sc,sigy1,f,yc,phi1)
  ftest=f+0.001*f
  call Meffective(a,b,c,ad,bd,cd,ftest,mul,k11,mu2,k2,MHS,path)
  do 1003 i=1,6
    do 1004 j=1,6
      MHS(i,j)=3.0*mul*MHS(i,j)
1004  continue
1003  continue
  call yieldtest(MHS,sc,sigy1,ftest,yc,phi2)
  dphidf=(phi2-phi1)/(ftest-f)
  H=0.0
  H=-dphidf*(1.0-f)*(nc(1)+nc(2)+nc(3))
endif
c----- step B -- calculating dphi/dwi1
if (evolwi.eq..true.) then
  wiltest=wil+0.001*wil
  ate=c/wiltest
  call Meffective(ate,b,c,ate,b,c,f,mul,k11,mu2,k2,
  &                                         MHS,path)
  do 2003 i=1,6
    do 2004 j=1,6
      MHS(i,j)=3.0*mul*MHS(i,j)
2004  continue
2003  continue
  call yieldtest(MHS,sc,sigy1,f,yc,phi2)
  dphidw1=(phi2-phi1)/(wiltest-wil)
  dummy(1)=Amat(3,1)-Amat(1,1)
  dummy(2)=Amat(3,2)-Amat(1,2)
  dummy(3)=Amat(3,3)-Amat(1,3)
  dummy(4)=Amat(3,4)-Amat(1,4)
  dummy(5)=Amat(3,5)-Amat(1,5)
  dummy(6)=Amat(3,6)-Amat(1,6)
  do 400 i=1,6
    dummy5(i)=nc(i)
400  continue
  call rowcolumnprod(dummy,dummy5,dum5)
  H=H-dphidw1*wil*dum5
endif
c----- step C -- calculating dphi/dwi2
if (evolwi.eq..true.) then
  wi2test=wi2+0.001*wi2
  bte=c/wi2test
  call Meffective(a,bte,c,a,bte,c,f,mul,k11,mu2,k2,
  &                                         MHS,path)
  do 3003 i=1,6
    do 3004 j=1,6
      MHS(i,j)=3.0*mul*MHS(i,j)
3004  continue
3003  continue
  call yieldtest(MHS,sc,sigy1,f,yc,phi2)

```

```

dphidwi2=(phi2-phi1)/(wi2test-wi2)
do 401 i=1,6
  dummy5(i)=nc(i)
401 continue
  dummy(1)=Amat(3,1)-Amat(2,1)
  dummy(2)=Amat(3,2)-Amat(2,2)
  dummy(3)=Amat(3,3)-Amat(2,3)
  dummy(4)=Amat(3,4)-Amat(2,4)
  dummy(5)=Amat(3,5)-Amat(2,5)
  dummy(6)=Amat(3,6)-Amat(2,6)
  call rowcolumnprod(dummy,dummy5,dum10)
  H=H-dphidwi2*wi2*dum10
endif
c-----L=L+H
c-----
do 450 i=1,6
  dummy5(i)=nc(i)
450 continue
if(debug.eq..true.) then
write(15,*)'guess5',L
call flush(15)
endif
call tenmatprod(Ce,strainc,sigec)
call rowcolumnprod(nc,sigec,dlam)
dlam=dlam/L
999 return
end

subroutine yieldtest(mhs,sig,sigy1,f,yc,yf)
real*8 mhs(6,6),sig(6),dummy(6),sigy1,f,yf
logical yc
yc=.false.
call tenmatprod(MHS,sig,dummy)
call rowcolumnprod(sig,dummy,yf)
yf=yf/((1.0-f)*sigy1)
yf=sigy1
if (yf.gt.0.0) then
  yc=.true.
else
  yc=.false.
endif
return
end

c----- This routine expresses 4th order tensors as 6x6 matrices
c     in the Voigt notation
subroutine ten2matrix(l1,l2)
real*8 l1(3,3,3,3),l2(6,6)
  l(1,1)=l1(1,1,1,1)
  l(1,2)=l1(1,1,2,2)
  l(1,3)=l1(1,1,3,3)
  l(1,4)=dsqrt(2.0d0)*l1(1,1,1,2)
  l(1,5)=dsqrt(2.0d0)*l1(1,1,2,3)
  l(1,6)=dsqrt(2.0d0)*l1(1,1,3,1)
  l(2,1)=l1(2,2,1,1)
  l(2,2)=l1(2,2,2,2)
  l(2,3)=l1(2,2,3,3)
  l(2,4)=dsqrt(2.0d0)*l1(2,2,1,2)
  l(2,5)=dsqrt(2.0d0)*l1(2,2,2,3)
  l(2,6)=dsqrt(2.0d0)*l1(2,2,3,1)
  l(3,1)=l1(3,3,1,1)
  l(3,2)=l1(3,3,2,2)
  l(3,3)=l1(3,3,3,3)
  l(3,4)=dsqrt(2.0d0)*l1(3,3,1,2)
  l(3,5)=dsqrt(2.0d0)*l1(3,3,2,3)
  l(3,6)=dsqrt(2.0d0)*l1(3,3,3,1)
  l(4,1)=dsqrt(2.0d0)*l1(1,2,1,1)
  l(4,2)=dsqrt(2.0d0)*l1(1,2,2,2)
  l(4,3)=dsqrt(2.0d0)*l1(1,2,3,3)
  l(4,4)=(2.0)*l1(1,2,1,2)
  l(4,5)=(2.0)*l1(1,2,2,3)
  l(4,6)=(2.0)*l1(1,2,3,1)
  l(5,1)=dsqrt(2.0d0)*l1(2,3,1,1)
  l(5,2)=dsqrt(2.0d0)*l1(2,3,2,2)
  l(5,3)=dsqrt(2.0d0)*l1(2,3,3,3)
  l(5,4)=(2.0)*l1(2,3,1,2)
  l(5,5)=(2.0)*l1(2,3,2,3)
  l(5,6)=(2.0)*l1(2,3,3,1)
  l(6,1)=dsqrt(2.0d0)*l1(1,3,1,1)
  l(6,2)=dsqrt(2.0d0)*l1(1,3,2,2)
  l(6,3)=dsqrt(2.0d0)*l1(1,3,3,3)
  l(6,4)=(2.0)*l1(1,3,1,2)
  l(6,5)=(2.0)*l1(1,3,2,3)

```

```

l(6,6)=(2.0)*ll(1,3,3,1)
return
end

C----- This is to rotate fourth order tensors
subroutine rot4order(ll,q,lnew)
real*8 ll(3,3,3,3),q(3,3),e(9),f(27),d(3)
real*8 lnew(3,3,3,3)
integer i,j,k,l
do 10 i=1,3
  do 11 j=1,3
    do 12 k=1,3
      do 13 l=1,3
        f(1)=q(1,1)*ll(1,1,1,1)+q(1,2)*ll(1,1,1,2)+q(1,3)*ll(1,1,1,3)
        f(2)=q(1,1)*ll(1,1,2,1)+q(1,2)*ll(1,1,2,2)+q(1,3)*ll(1,1,2,3)
        f(3)=q(1,1)*ll(1,1,3,1)+q(1,2)*ll(1,1,3,2)+q(1,3)*ll(1,1,3,3)
        f(4)=q(1,1)*ll(1,2,1,1)+q(1,2)*ll(1,2,1,2)+q(1,3)*ll(1,2,1,3)
        f(5)=q(1,1)*ll(1,2,2,1)+q(1,2)*ll(1,2,2,2)+q(1,3)*ll(1,2,2,3)
        f(6)=q(1,1)*ll(1,2,3,1)+q(1,2)*ll(1,2,3,2)+q(1,3)*ll(1,2,3,3)
        f(7)=q(1,1)*ll(1,3,1,1)+q(1,2)*ll(1,3,1,2)+q(1,3)*ll(1,3,1,3)
        f(8)=q(1,1)*ll(1,3,2,1)+q(1,2)*ll(1,3,2,2)+q(1,3)*ll(1,3,2,3)
        f(9)=q(1,1)*ll(1,3,3,1)+q(1,2)*ll(1,3,3,2)+q(1,3)*ll(1,3,3,3)
        f(10)=q(1,1)*ll(2,1,1,1)+q(1,2)*ll(2,1,1,2)+q(1,3)*ll(2,1,1,3)
        f(11)=q(1,1)*ll(2,1,2,1)+q(1,2)*ll(2,1,2,2)+q(1,3)*ll(2,1,2,3)
        f(12)=q(1,1)*ll(2,1,3,1)+q(1,2)*ll(2,1,3,2)+q(1,3)*ll(2,1,3,3)
        f(13)=q(1,1)*ll(2,2,1,1)+q(1,2)*ll(2,2,1,2)+q(1,3)*ll(2,2,1,3)
        f(14)=q(1,1)*ll(2,2,2,1)+q(1,2)*ll(2,2,2,2)+q(1,3)*ll(2,2,2,3)
        f(15)=q(1,1)*ll(2,2,3,1)+q(1,2)*ll(2,2,3,2)+q(1,3)*ll(2,2,3,3)
        f(16)=q(1,1)*ll(2,3,1,1)+q(1,2)*ll(2,3,1,2)+q(1,3)*ll(2,3,1,3)
        f(17)=q(1,1)*ll(2,3,2,1)+q(1,2)*ll(2,3,2,2)+q(1,3)*ll(2,3,2,3)
        f(18)=q(1,1)*ll(2,3,3,1)+q(1,2)*ll(2,3,3,2)+q(1,3)*ll(2,3,3,3)
        f(19)=q(1,1)*ll(3,1,1,1)+q(1,2)*ll(3,1,1,2)+q(1,3)*ll(3,1,1,3)
        f(20)=q(1,1)*ll(3,1,2,1)+q(1,2)*ll(3,1,2,2)+q(1,3)*ll(3,1,2,3)
        f(21)=q(1,1)*ll(3,1,3,1)+q(1,2)*ll(3,1,3,2)+q(1,3)*ll(3,1,3,3)
        f(22)=q(1,1)*ll(3,2,1,1)+q(1,2)*ll(3,2,1,2)+q(1,3)*ll(3,2,1,3)
        f(23)=q(1,1)*ll(3,2,2,1)+q(1,2)*ll(3,2,2,2)+q(1,3)*ll(3,2,2,3)
        f(24)=q(1,1)*ll(3,2,3,1)+q(1,2)*ll(3,2,3,2)+q(1,3)*ll(3,2,3,3)
        f(25)=q(1,1)*ll(3,3,1,1)+q(1,2)*ll(3,3,1,2)+q(1,3)*ll(3,3,1,3)
        f(26)=q(1,1)*ll(3,3,2,1)+q(1,2)*ll(3,3,2,2)+q(1,3)*ll(3,3,2,3)
        f(27)=q(1,1)*ll(3,3,3,1)+q(1,2)*ll(3,3,3,2)+q(1,3)*ll(3,3,3,3)
        e(1)=q(k,1)*f(1)+q(k,2)*f(2)+q(k,3)*f(3)
        e(2)=q(k,1)*f(4)+q(k,2)*f(5)+q(k,3)*f(6)
        e(3)=q(k,1)*f(7)+q(k,2)*f(8)+q(k,3)*f(9)
        e(4)=q(k,1)*f(10)+q(k,2)*f(11)+q(k,3)*f(12)
        e(5)=q(k,1)*f(13)+q(k,2)*f(14)+q(k,3)*f(15)
        e(6)=q(k,1)*f(16)+q(k,2)*f(17)+q(k,3)*f(18)
        e(7)=q(k,1)*f(19)+q(k,2)*f(20)+q(k,3)*f(21)
        e(8)=q(k,1)*f(22)+q(k,2)*f(23)+q(k,3)*f(24)
        e(9)=q(k,1)*f(25)+q(k,2)*f(26)+q(k,3)*f(27)
        d(1)=q(j,1)*e(1)+q(j,2)*e(2)+q(j,3)*e(3)
        d(2)=q(j,1)*e(4)+q(j,2)*e(5)+q(j,3)*e(6)
        d(3)=q(j,1)*e(7)+q(j,2)*e(8)+q(j,3)*e(9)
        lnew(i,j,k,l)=q(i,1)*d(1)+q(i,2)*d(2)+q(i,3)*d(3)
13   continue
12   continue
11   continue
10  continue
  return
end

C----- This routine expresses 6x6 matrices back in tensorial(4th order) form.
c
c The matrix is in Voigt Notation.
subroutine mat2tensor(l,11)
real*8 l(6,6),ll(3,3,3,3)
ll(1,1,1,1)=l(1,1)
ll(1,1,2,2)=l(1,2)
ll(1,1,3,3)=l(1,3)
ll(1,1,1,2)=l(1,4)/dsqrt(2.0d0)
ll(1,1,2,3)=l(1,5)/dsqrt(2.0d0)
ll(1,1,3,1)=l(1,6)/dsqrt(2.0d0)
ll(2,2,1,1)=l(2,1)
ll(2,2,2,2)=l(2,2)
ll(2,2,3,3)=l(2,3)
ll(2,2,1,2)=l(2,4)/dsqrt(2.0d0)
ll(2,2,2,3)=l(2,5)/dsqrt(2.0d0)
ll(2,2,3,1)=l(2,6)/dsqrt(2.0d0)
ll(3,3,1,1)=l(3,1)
ll(3,3,2,2)=l(3,2)
ll(3,3,3,3)=l(3,3)
ll(3,3,1,2)=l(3,4)/dsqrt(2.0d0)
ll(3,3,2,3)=l(3,5)/dsqrt(2.0d0)

```

```

11(3,3,3,1)=l(3,6)/dsqrt(2.0d0)
11(1,2,1,1)=l(4,1)/dsqrt(2.0d0)
11(1,2,2,2)=l(4,2)/dsqrt(2.0d0)
11(1,2,3,3)=l(4,3)/dsqrt(2.0d0)
11(1,2,1,2)=l(4,4)/2.0
11(1,2,2,3)=l(4,5)/2.0
11(1,2,3,1)=l(4,6)/2.0
11(2,3,1,1)=l(5,1)/dsqrt(2.0d0)
11(2,3,2,2)=l(5,2)/dsqrt(2.0d0)
11(2,3,3,3)=l(5,3)/dsqrt(2.0d0)
11(2,3,1,2)=l(5,4)/2.0
11(2,3,2,3)=l(5,5)/2.0
11(2,3,3,1)=l(5,6)/2.0
11(3,1,1,1)=l(6,1)/dsqrt(2.0d0)
11(3,1,2,2)=l(6,2)/dsqrt(2.0d0)
11(3,1,3,3)=l(6,3)/dsqrt(2.0d0)
11(3,1,1,2)=l(6,4)/2.0
11(3,1,2,3)=l(6,5)/2.0
11(3,1,3,1)=l(6,6)/2.0
11(1,1,2,1)=l1(1,1,1,2)
11(1,1,3,2)=l1(1,1,2,3)
11(1,1,1,3)=l1(1,1,3,1)
11(2,2,2,1)=l1(2,2,1,2)
11(2,2,3,2)=l1(2,2,2,3)
11(2,2,1,3)=l1(2,2,3,1)
11(3,3,2,1)=l1(3,3,1,2)
11(3,3,3,2)=l1(3,3,2,3)
11(3,3,1,3)=l1(3,3,3,1)
11(2,1,1,1)=l1(1,2,1,1)
11(2,1,2,2)=l1(1,2,2,2)
11(2,1,3,3)=l1(1,2,3,3)
11(2,1,1,2)=l1(1,2,1,2)
11(2,1,2,3)=l1(1,2,2,3)
11(2,1,3,1)=l1(1,2,3,1)
11(2,1,2,1)=l1(1,2,1,2)
11(2,1,3,2)=l1(1,2,2,3)
11(2,1,1,3)=l1(1,2,3,1)
11(1,2,2,1)=l1(1,2,1,2)
11(1,2,3,2)=l1(1,2,2,3)
11(1,2,1,3)=l1(1,2,3,1)
11(3,2,1,1)=l1(2,3,1,1)
11(3,2,2,2)=l1(2,3,2,2)
11(3,2,3,3)=l1(2,3,3,3)
11(3,2,1,2)=l1(2,3,1,2)
11(3,2,2,3)=l1(2,3,2,3)
11(3,2,3,1)=l1(2,3,3,1)
11(3,2,2,1)=l1(2,3,1,2)
11(3,2,3,2)=l1(2,3,2,3)
11(3,2,1,3)=l1(2,3,3,1)
11(2,3,2,1)=l1(2,3,1,2)
11(2,3,3,2)=l1(2,3,2,3)
11(2,3,1,3)=l1(2,3,3,1)
11(1,3,1,1)=l1(3,1,1,1)
11(1,3,2,2)=l1(3,1,2,2)
11(1,3,3,3)=l1(3,1,3,3)
11(1,3,1,2)=l1(3,1,1,2)
11(1,3,2,3)=l1(3,1,2,3)
11(1,3,3,1)=l1(3,1,3,1)
11(1,3,2,1)=l1(3,1,1,2)
11(1,3,3,2)=l1(3,1,2,3)
11(1,3,1,3)=l1(3,1,3,1)
11(3,1,2,1)=l1(3,1,1,2)
11(3,1,3,2)=l1(3,1,2,3)
11(3,1,1,3)=l1(3,1,3,1)
11(3,1,1,1)=l1(3,1,3,1)
return
end

```

```

SUBROUTINE ZBRAK(func,X1,X2,N,XB1,XB2,NB)
real*8 xb1,xb2,x1,x2,x,dx,fp,fc,func
integer n,nb,i,nbb
logical yield, check,neg
logical zb
common /mkdata2/yield,check,neg
common /zb1/zb
external func
NBB=NB
NB=0
X=X1
DX=(X2-X1)/N
FP=func(X)
if (neg.eq..true.) then
  write(15,'*)'returning in ZBRAK'
  call flush(15)
  return
end

```

```
endif
DO 11 I=1,N
  X=X+DX
  FC=func(X)
c  if (zb.eq..true.) then
    write(15,*)'dlam',X, 'f',fc
    endif
c  if (neg.eq..true.) then
    write(15,*)"returning in ZBRAK_2"
    call flush(15)
    return
  endif
  IF(FC*FP.LT.0.) THEN
    NB=NB+1
    XB1=X-DX
    XB2=X
    write(15,*)"info',xb1,xb2,fp,fc
    call flush(15)
  ENDIF
  FP=FC
  IF(NBB.EQ.NB) then
    write(15,*)"info2',xb1,xb2,func(xb1),func(xb2)
c
  RETURN
  endif
11  CONTINUE
  RETURN
END
```